

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS

Motor type: **GP100** FS: 254T - 4p - 15 hp -

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data without

U [V]	Δ/Y	f [Hz]	P [HP]	P [kW]	n [rpm]	I Load [Amps]					Nom. Eff Load [%]			Pwr. Factor Load [%]			Torque [lb-ft]	T _A /T _N LRT [%]	T _k /T _N BDT [%]
						4/4	3/4	1/2	0	LRC	4/4	3/4	2/4	4/4	3/4	2/4			
460	Y	60	15.00	11.00	1,770	19.00	15.20	11.80	8.50	116.0	92.4	92.8	92.3	80.0	74.7	64.5	44.0	184	234
230	YY	60	15.00	11.00	1,770	38.00	30.39	23.59	17.00	232.0	92.4	92.8	92.3	80.0	74.7	64.5	44.0	184	234

Frame Type: 254T	Type of constr.: (E) Foot mounted - C-Face	Ins. Cl.: Standard Class F Insulation	Motor Prot.: (A) Without Protection	NEMA Des.: B	S.F.: 1.15
Mtr. WT: 242		Temp. Rise Cl.: B	Amb. Temp.: + 40 to -20 °C @1000 m	kVA: G	I.P.: 55

Mechanical data

Sound level (SPL / SWL) at 60 Hz	61.0 dB(A) / 73.0 dB(A)		Thickener	Polyurea					
Octave Band Center Frequencies Hertz			Safe Stall Time Hot	21 s					
	250	500	1000	2000	4000	8000	Hz	Safe Stall Time Cold	33 s
SPL@3	47.0	53.0	59.0	56.0	47.0	38.0	dB(A)	Frame material	cast iron
Moment of inertia	1.7 Lb-ft ²		Color, paint shade	Standard Paint - RAL7030					
Ext Load Inertia Capability:	75.0 Lb ft ²		Coating (paint finish)	Standard Alkyed + Epoxy (C2)					
Bearings			Ventilation Type						
Bearing DE NDE	6209 ZZ C3 S0		6209 ZZ C3 S0	Method of cooling	TEFC				
Bearing_Type	Ball Bearing		Ball Bearing	Direction of rotation	Bidirectional				
AFBMA:	45BC02JPP30		45BC02JPP30	Fan Material	Polypropylen				
Grease			VFD	CT: 4:1 VT: 20:1					
Capacity	0.50 oz		0.50 oz	Space heaters	without				
Grease Type:	Exxon Mobile EM		Brake:	without					

Terminal box


Lead Wire Connection	9 LEAD - WYE				Terminal box position	(3) F-1, Standard Floor Mount, T. Box LHS
Voltage	L1	L1	L1	Connected together	Material of terminal box	Aluminium
LOW	T1 T7	T2 T8	T3 T9	T4 T5 T6	Cable entry	1.25" NPT
HIGH	T1	T2	T3	T4 T7-T5 T8-T6 T9		

Notes:

I_r/I_N = locked rotor current / current nominal
M_r/M_N = locked rotor torque / torque nominal
M_d/M_N = break down torque / nominal torque

3) Value is valid only for DOL operation with motor design IC411
2) at rated power / at full load

responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	<i>Technical data are subject to change! There may be discrepancies between software and hardware versions</i>
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	document type datasheet	document status released	customer	
	title 1LE2221-2BB11-4EA3-Z 809	document number	rev. 01	creation date 2021-04-22 08:33
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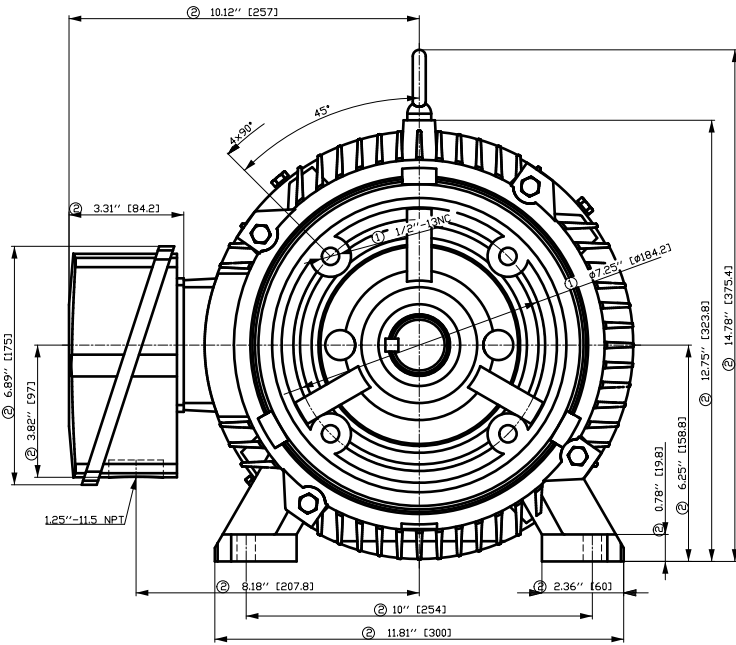
Motor type: GP100 FS: 254T - 4p - 15 hp -

Special design

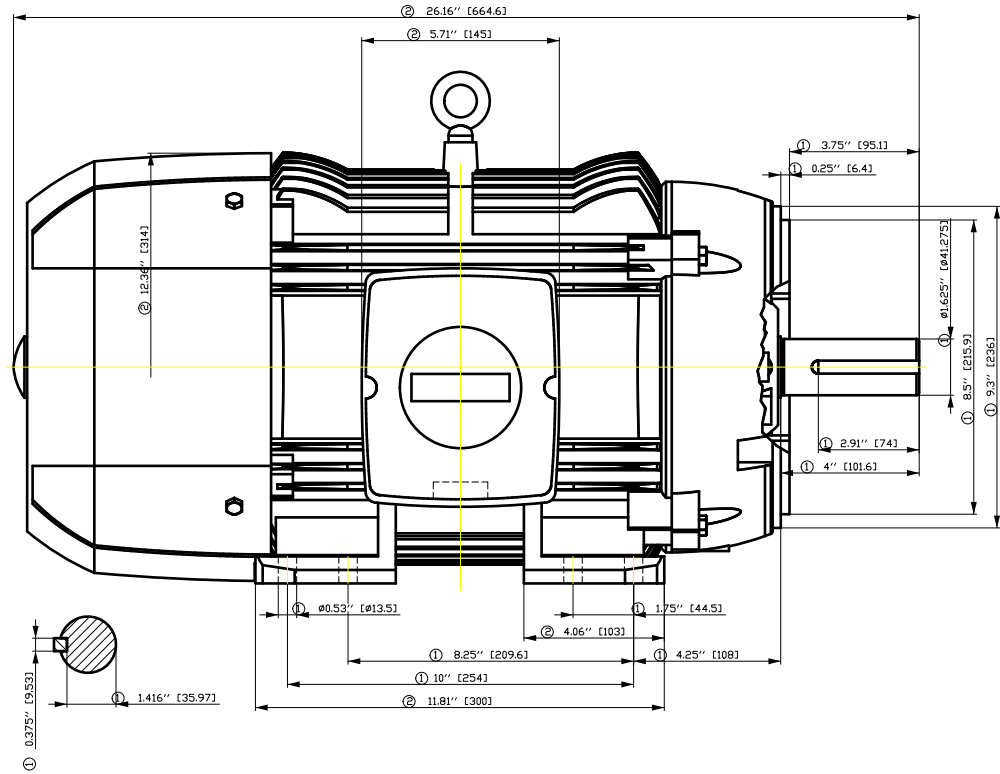
B09	Export packing sea freight - Siemens standard

Notes:

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- ① Tolerances according to NEMA std.
- ② All these dimensions corresponding to assemblies and castings shall have a tolerance as per DIN standard 1686-GTB 19.
- ③ Not according to NEMA std.

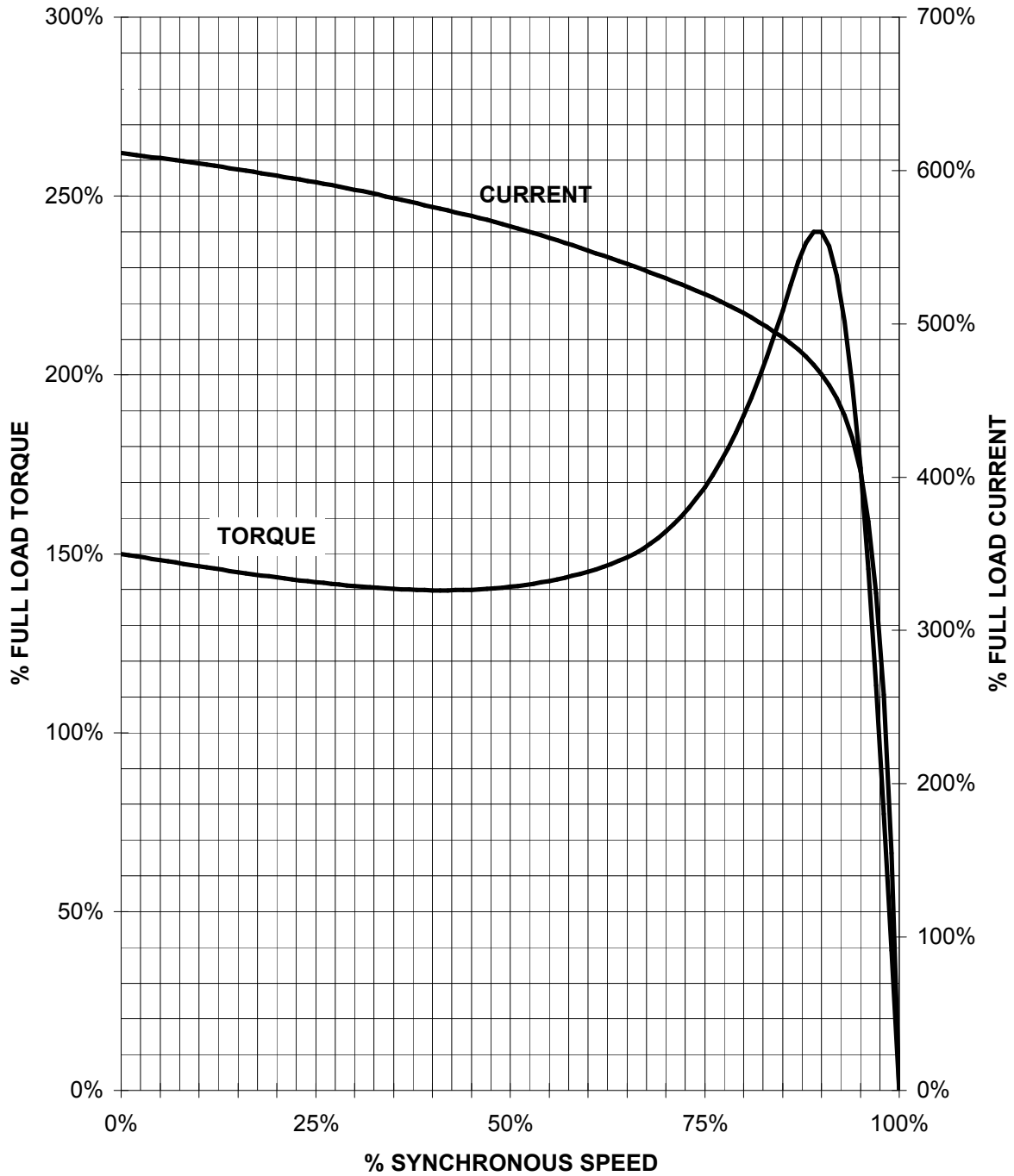


Tolerance	Surface	Material	Weight	Scale
F5ÖGGGFÉZÓOFFÉ ÖCHEZ ÖEJ	Author Creator Approval Department Change Order	ÖB ^}•q}xh/æ q* T æ : ^æ@` }*	Ö	{ {
SIEMENS	Doc. State	Item No	Paper Size	
	Revision	Doc No	1st Language 2nd Language	
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SIEMENS INDUSTRY, INC.

HP 15 VOLTS < 600V RPM 1800 TYPE GP100
HZ 60 PHASE 3 FRAME 254T NEMA B

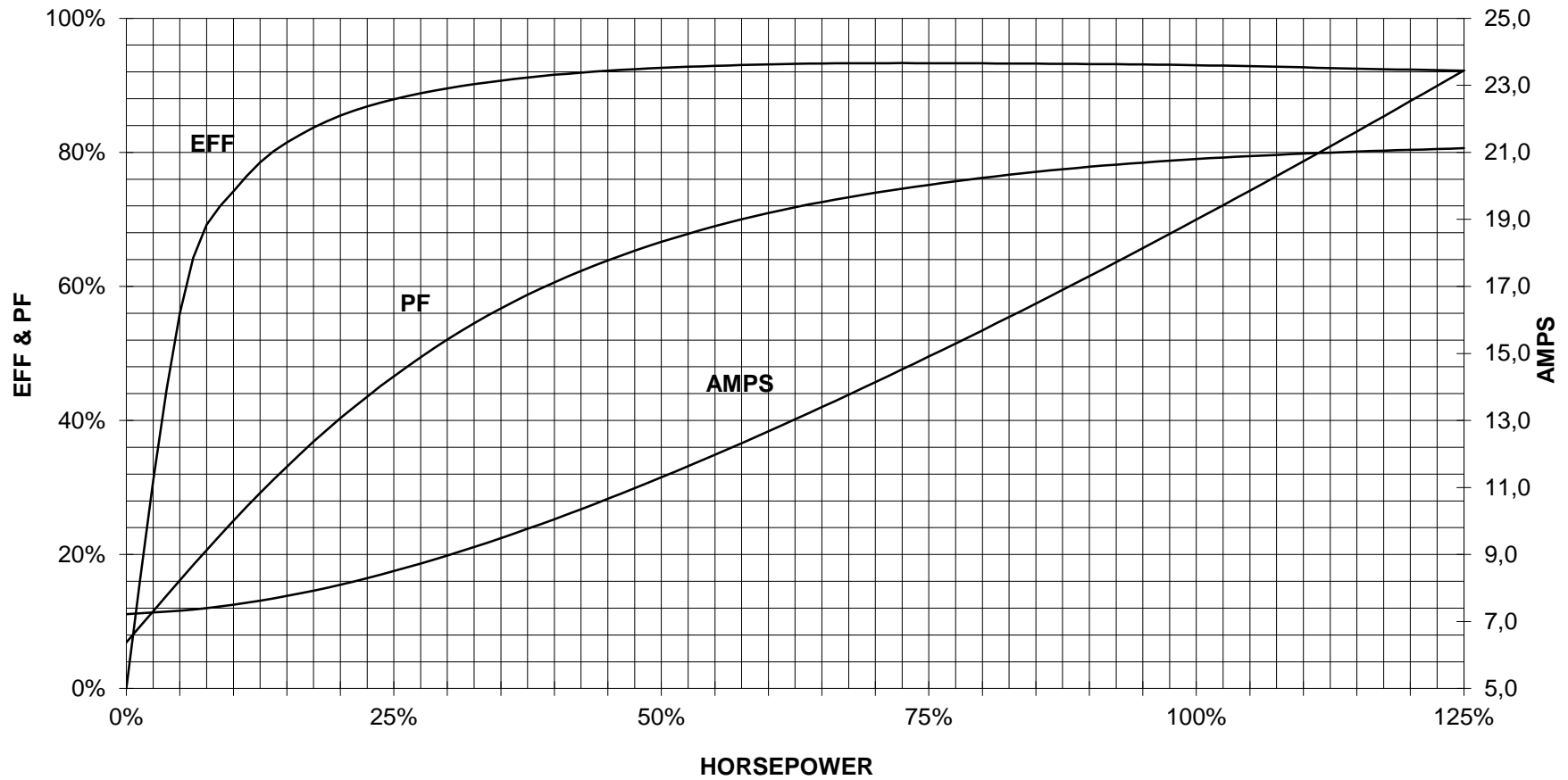
TORQUE & CURRENT VS. SPEED



CUSTOMER: _____ ORDER#: _____

15 HP 1800 RPM 254T FRAME 460 VOLTS 3 PHASE NEMA DESIGN B

SIEMENS INDUSTRY, INC.
PERFORMANCE CURVE
GP100

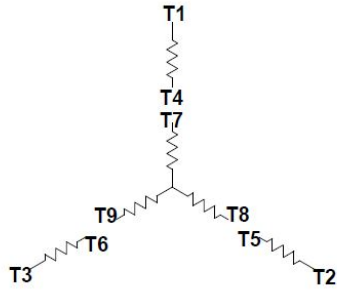


CUSTOMER _____ ORDER # _____ PO # _____

PERFORMANCE BASED ON DESIGN CALCULATIONS. SUBJECT TO CHANGE WITHOUT NOTICE.

REV. 1

Main terminal diagram



9 LEAD WYE						
Volts	LINES			CONNECTED TOGETHER	CONN.	
	L1	L2	L3			
LOW	T1 T7	T2 T6	T3 T9	T4 T5 T6	YY	
HIGH	T1	T2	T3	T4 T7-T5 T8-T6 T9	Y	

responsible dep. DI MC LVM	technical reference	created by	approved by	Project
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