

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS

Motor type: **GP100A** FS: 215T - 2p - 10 hp -

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data without

U [V]	Δ/Y	f [Hz]	P [HP]	P [kW]	n [rpm]	I Load [Amps]					LRC	Nom. Eff Load [%]			Pwr. Factor Load [%]			Torque [lb-ft]	T _A /T _N LRT [%]	T _k /T _N BDT [%]
						4/4	3/4	1/2	0	4/4		3/4	2/4	4/4	3/4	2/4				
460	Y	60	10.00	7.50	3,515	11.50	8.70	6.30	3.50	81.0	90.2	91.1	91.0	90.3	88.8	81.5	15.0	180	440	
230	YY	60	10.00	7.50	3,515	23.00	17.36	12.63	7.00	162.0	90.2	91.1	91.0	90.3	88.8	81.5	15.0	180	440	

Frame Type: 215T	Type of constr.: (A) Foot mounted - End shield	Ins. Cl.: Standard Class F Insulation	Motor Prot.: (A) Without Protection	NEMA Des.: B	S.F.: 1.15
Mtr. WT: 157		Temp. Rise Cl.: B	Amb. Temp.: + 40 to -20 °C @1000 m	kVA: H	I.P.: 55

Mechanical data

Sound level (SPL / SWL) at 60 Hz	66.0 dB(A) / 78.0 dB(A)							Thickener	Polyurea
Octave Band Center Frequencies Hertz								Safe Stall Time Hot	14 s
	250	500	1000	2000	4000	8000	Hz	Safe Stall Time Cold	28 s
SPL@3	53.0	55.0	63.0	62.0	58.0	47.0	dB(A)	Frame material	aluminum
Moment of inertia	0.5 Lb-ft ²							Color, paint shade	Standard Paint - RAL7030
Ext Load Inertia Capability:	11.0 Lb ft ²							Coating (paint finish)	Standard Alkyed + Epoxy (C2)
Bearings								Ventilation Type	
Bearing DE NDE	6208 ZZ C3 S0			6208 ZZ C3 S0			Method of cooling	TEFC	
Bearing_Type	Ball Bearing			Ball Bearing			Direction of rotation	Bidirectional	
AFBMA:	40BC02JPP30			40BC02JPP30			Fan Material	Polypropylen	
Grease								VFD	CT: 4:1 VT: 20:1
Capacity	0.30 oz			0.30 oz			Space heaters	without	
Grease Type:	Exxon Mobile EM							Brake:	without

Terminal box


Lead Wire Connection	9 LEAD - WYE				Terminal box position	(3) F-1, Standard Floor Mount, T. Box LHS	
Voltage	L1	L1	L1	Connected together	Material of terminal box	Aluminium	
LOW	T1 T7	T2 T8	T3 T9	T4 T5 T6	Cable entry	1" NPT	
HIGH	T1	T2	T3	T4 T7-T5 T8-T6 T9			

Notes:

I_r/I_N = locked rotor current / current nominal
M_r/M_N = locked rotor torque / torque nominal
M_d/M_N = break down torque / nominal torque

3) Value is valid only for DOL operation with motor design IC411
2) at rated power / at full load

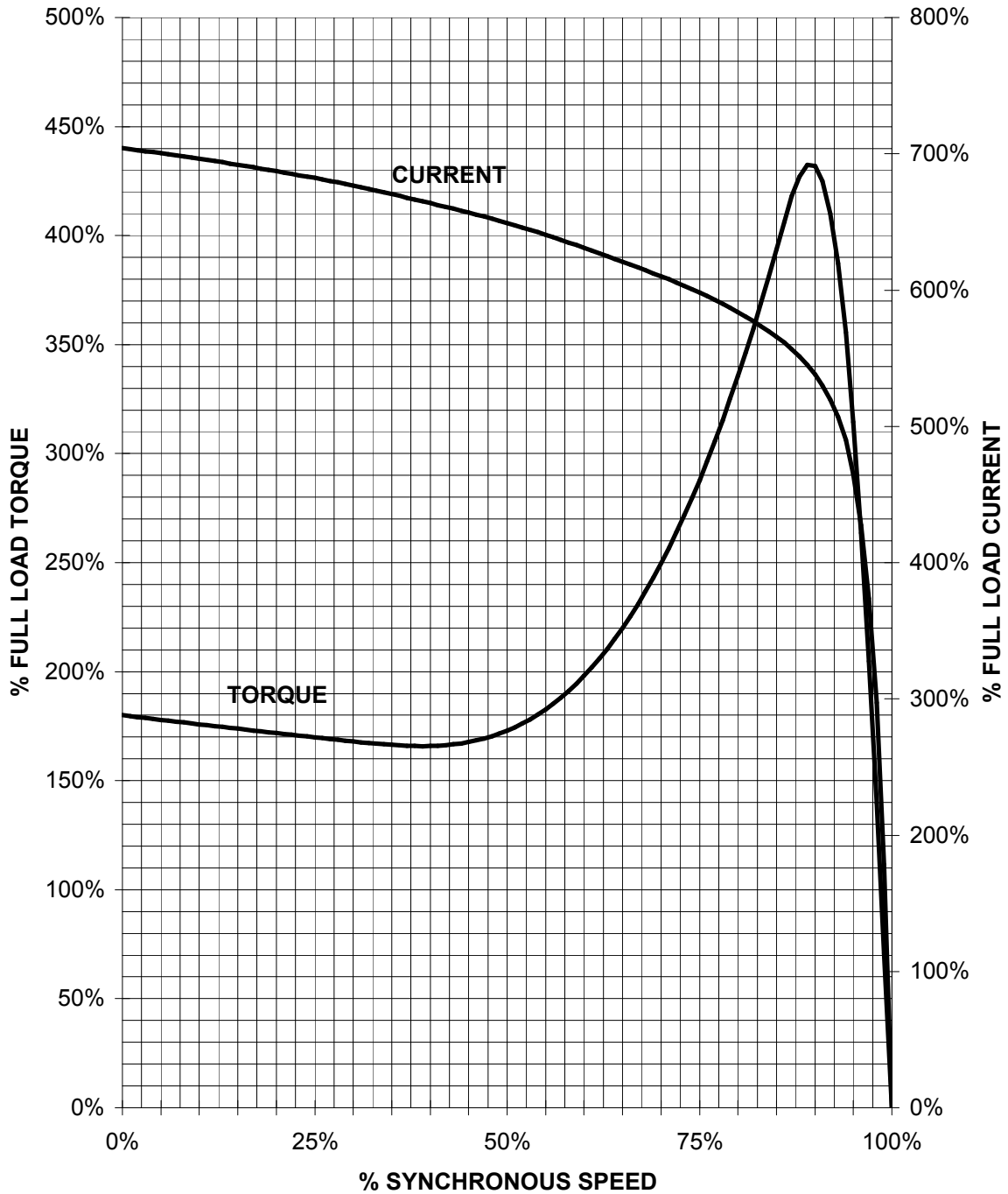
responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	<i>Technical data are subject to change! There may be discrepancies between software and hardware versions.</i>
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HP 10 VOLTS < 600V RPM 3600 TYPE GP100A
HZ 60 PHASE 3 FRAME 215T NEMA B

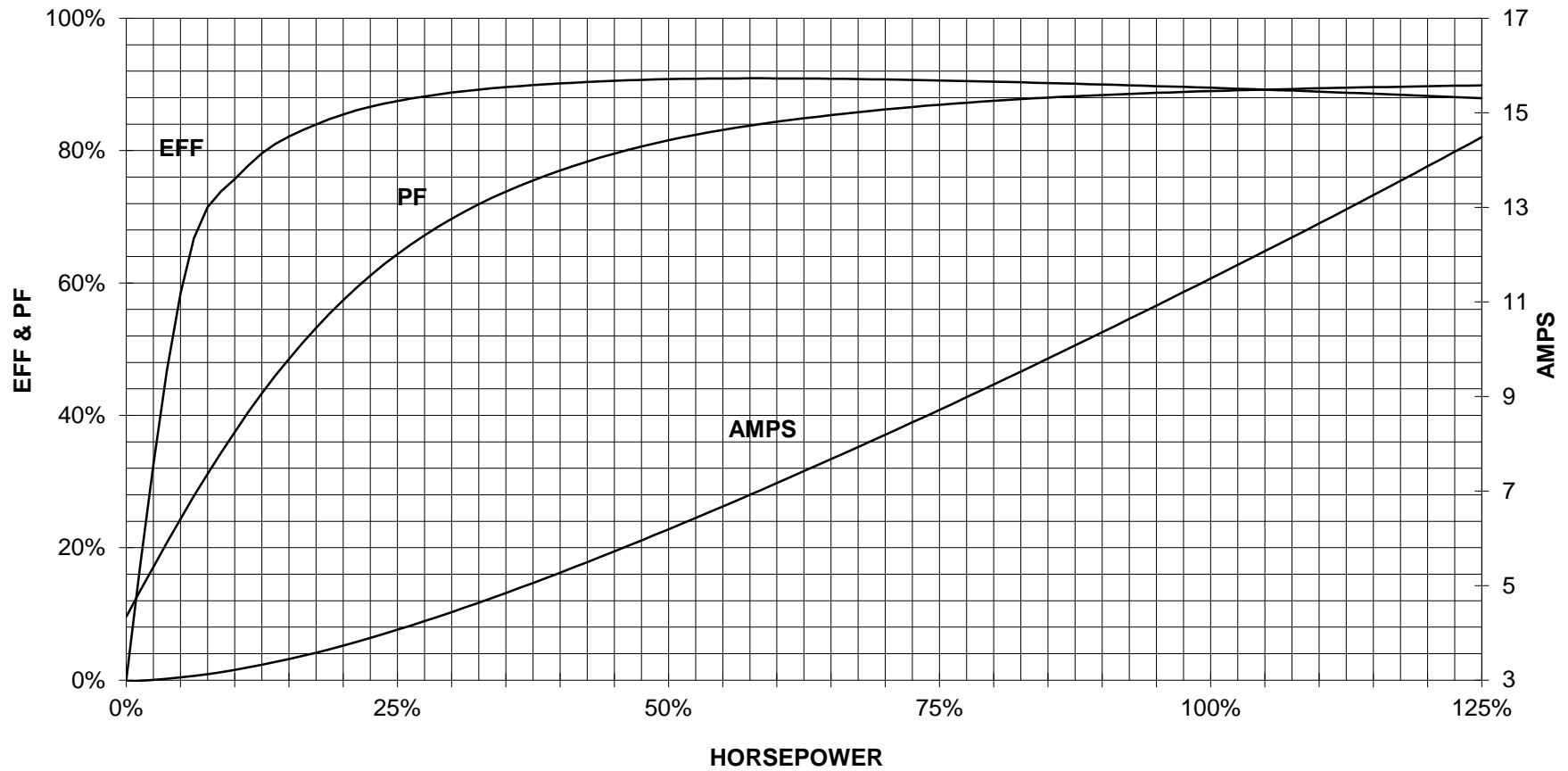
TORQUE & CURRENT VS. SPEED



CUSTOMER: _____ ORDER#: _____

10 HP 3600 RPM 215 FRAME 460 VOLTS 3 PHASE NEMA DESIGN B

SIEMENS INDUSTRY, INC.
PERFORMANCE CURVE
GP100A NP



CUSTOMER _____ ORDER # _____ PO # _____

PERFORMANCE BASED ON DESIGN CALCULATIONS. SUBJECT TO CHANGE WITHOUT NOTICE.

REV. 1

Main terminal diagram



9 LEAD WYE						
Volts	LINES			CONNECTED TOGETHER	CONN.	
	L1	L2	L3			
LOW	T1 T7	T2 T6	T3 T9	T4 T5 T6	YY	
HIGH	T1	T2	T3	T4 T7-T5 T8-T6 T9	Y	

responsible dep. DI MC LVM	technical reference	created by	approved by	Project
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