

MLFB-Ordering data

6SL3210-1KE24-4UF1



Client order no. : Order no. : Offer no. : Remarks : Item no. : Consignment no. : Project :

Rated da	ta
Input	
Number of phases	3 AC
Line voltage	380 480 V +10 % -20 %
Line frequency	47 63 Hz
Rated current (LO)	41.00 A
Rated current (HO)	39.00 A
Output	
Number of phases	3 AC
Rated voltage	400 V
Rated power IEC 400V (LO)	22.00 kW
Rated power NEC 480V (LO)	25.00 hp
Rated power IEC 400V (HO)	18.50 kW
Rated power NEC 480V (HO)	20.00 hp
Rated current (LO)	43.00 A
Rated current (HO)	37.00 A
Rated current (IN)	43.00 A
Max. output current	74.00 A
Pulse frequency	4 kHz
Output frequency for vector control	0 240 Hz
Output frequency for V/f control	0 550 Hz

Overload ca	pability
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Low Overload (LO)

 $150\ \%$ base load current IL for 3 s, followed by $110\ \%$ base load current IL for 57 s in a $300\ s$ cycle time

High Overload (HO)

 $200\,\%$ base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications		
Power factor λ	0.90 0.95	
Tower factor X	0.50 0.55	
Offset factor cos φ	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	72 dB	
Power loss	0.68 kW	
Filter class (integrated)	Unfiltered	

Ambient conditions		
Cooling	Air cooling using an integrated fan	
Cooling air requirement	0.055 m³/s (1.942 ft³/s)	
Installation altitude	1000 m (3280.84 ft)	
Ambient temperature		
Operation	-20 40 °C (-4 104 °F)	
Transport	-40 70 °C (-40 158 °F)	
Storage	-40 70 °C (-40 158 °F)	
Relative humidity		

Max. operation	95 % RH, condensation not permitted

Closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	



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NA. d	. data		Figure similar	
Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET, EtherNet/IP	
Size	FSD	Co	nnections	
Net weight	17.10 kg (37.70 lb)	Signal cable		
Width	200 mm (7.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)	
Height	472 mm (18.58 in)	Line side		
Depth	237 mm (9.33 in)	Version	screw-type terminal	
Inputs / out	tputs	Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)	
Standard digital inputs		Motor end		
Number	6	Version	Screw-type terminals	
Switching level: 0→1	11 V	Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)	
Switching level: 1→0	5 V	DC link (for braking resistor)		
Max. inrush current	15 mA	Version	Screw-type terminals	
Fail-safe digital inputs		Conductor cross-section	10.00 35.00 mm² (AWG 8 AWG 2)	
Number	1	Line length, max.	10 m (32.81 ft)	
Digital outputs		-		
Number as relay changeover contact	1	PE connection Max. motor cable length	Screw-type terminals	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	200 m (656.17 ft)	
Number as transistor	1	Unshielded	300 m (984.25 ft)	
Output (resistive load)	DC 30 V, 0.5 A	S	tandards	
Analog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)		,,,	
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC	
Switching threshold as digital in	put			
0→1	4 V			
1→0	1.6 V			
Analog outputs				
Number	1 (Non-isolated output)			

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

PTC/ KTY interface



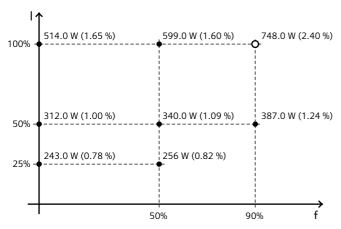
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Converter losses to EN 50598-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-51.71 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values