

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS

Motor type: **GP100** FS: **324T - 4p - 40 hp -**

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data without

U [V]	Δ/Y	f [Hz]	P [HP]	P [kW]	n [rpm]	I Load [Amps]					LRC	Nom. Eff Load [%]			Pwr. Factor Load [%]			Torque [lb-ft]	T _A /T _N LRT [%]	T _k /T _N BDT [%]
						4/4	3/4	1/2	0	4/4		3/4	2/4	4/4	3/4	2/4				
460	Δ	60	40.00	30.00	1,780	46.00	36.00	26.50	15.00	290.0	94.1	94.1	94.3	86.0	83.0	75.0	118.0	180	231	
230	$\Delta\Delta$	60	40.00	30.00	1,780	92.00	71.93	52.96	30.00	580.0	94.1	94.1	94.3	86.0	83.0	75.0	118.0	180	231	

Frame Type: 324T	Type of constr.: (A) Foot mounted - End shield	Ins. Cl.: Standard Class F Insulation	Motor Prot.: (A) Without Protection	NEMA Des.: B	S.F.: 1.15
Mtr. WT: 636		Temp. Rise Cl.: B	Amb. Temp.: + 40 to -20 °C @1000 m	kVA: G	I.P.: 55

Mechanical data

Sound level (SPL / SWL) at 60 Hz	64.0 dB(A) / 75.0 dB(A)							Thickener	Polyurea
Octave Band Center Frequencies Hertz								Safe Stall Time Hot	22 s
	250	500	1000	2000	4000	8000	Hz	Safe Stall Time Cold	45 s
SPL@3	52.0	59.0	59.0	57.0	53.0	50.0	dB(A)	Frame material	cast iron
Moment of inertia	9.3 Lb-ft ²							Color, paint shade	Standard Paint - RAL7030
Ext Load Inertia Capability:	189.0 Lb ft ²							Coating (paint finish)	Standard Alkyed + Epoxy (C2)
Bearings								Ventilation Type	
Bearing DE NDE	6312 Z C3 S0			6210 ZZ C3 S0			Method of cooling	TEFC	
Bearing_Type	Ball Bearing			Ball Bearing			Direction of rotation	Bidirectional	
AFBMA:	60BC03JP30			50BC02JPP30			Fan Material	Polypropylen ESD	
Grease								VFD	CT: 4:1 VT: 20:1
Capacity	5.50 oz			2.30 oz			Space heaters	without	
Grease Type:	Exxon Mobile EM							Brake:	without

Terminal box


Lead Wire Connection	9 LEAD - DELTA				Terminal box position	(3) F-1, Standard Floor Mount, T. Box LHS
Voltage	L1	L1	L1	Connected together	Material of terminal box	Stamped Steel
LOW	T1 T7 T6	T2 T8 T4	T3 T9 T5	----	Cable entry	2.5" NPT
HIGH	T1	T2	T3	T4 T7-T5 T8-T6 T9		

Notes:

I_L/I_N = locked rotor current / current nominal
 M_L/M_N = locked rotor torque / torque nominal
 M_d/M_N = break down torque / nominal torque

3) Value is valid only for DOL operation with motor design IC411
 2) at rated power / at full load

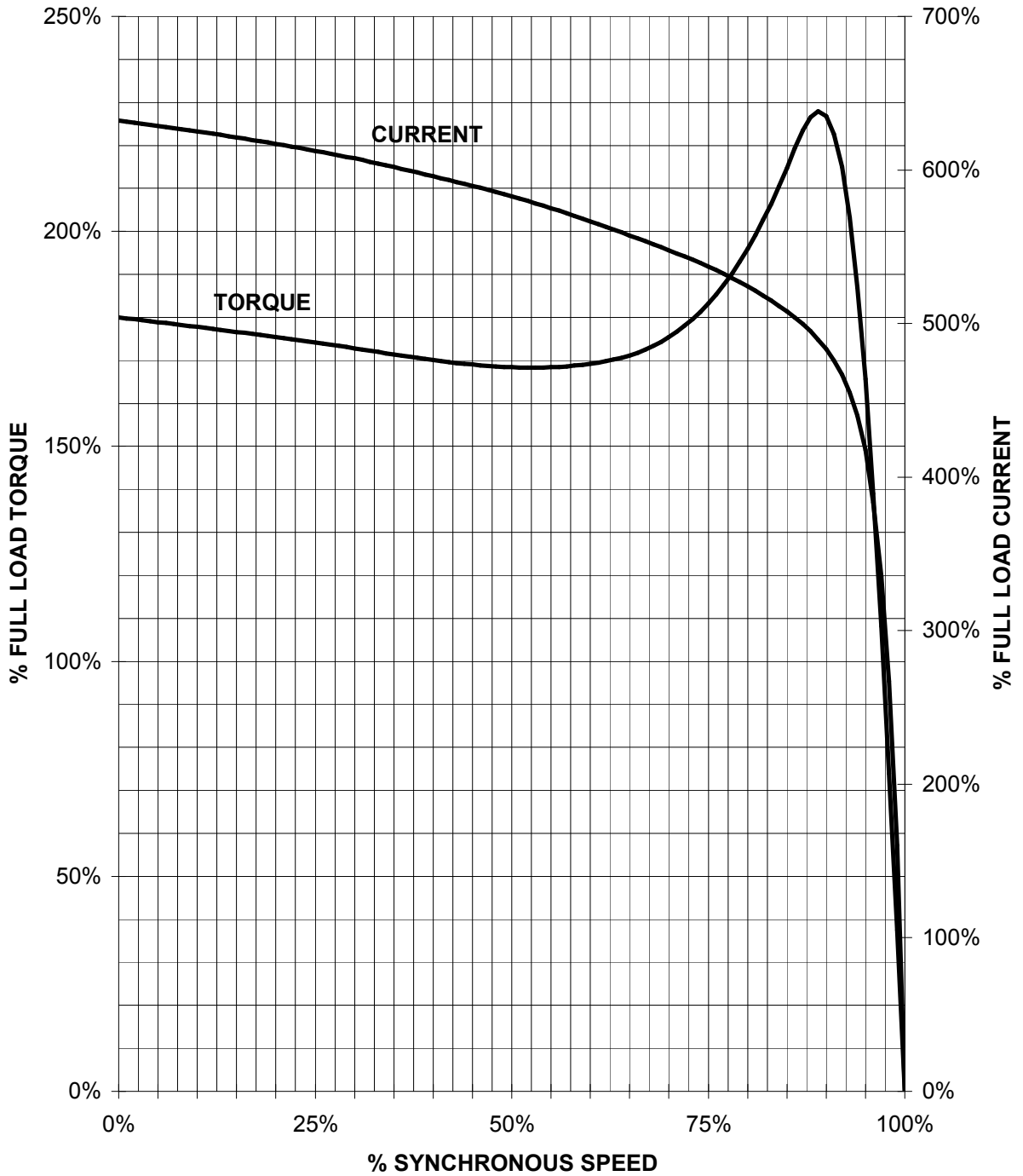
responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	<i>Technical data are subject to change! There may be discrepancies between software and hardware versions</i>
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HP 40 VOLTS < 600V RPM 1800 TYPE GP100
HZ 60 PHASE 3 FRAME 324T NEMA B

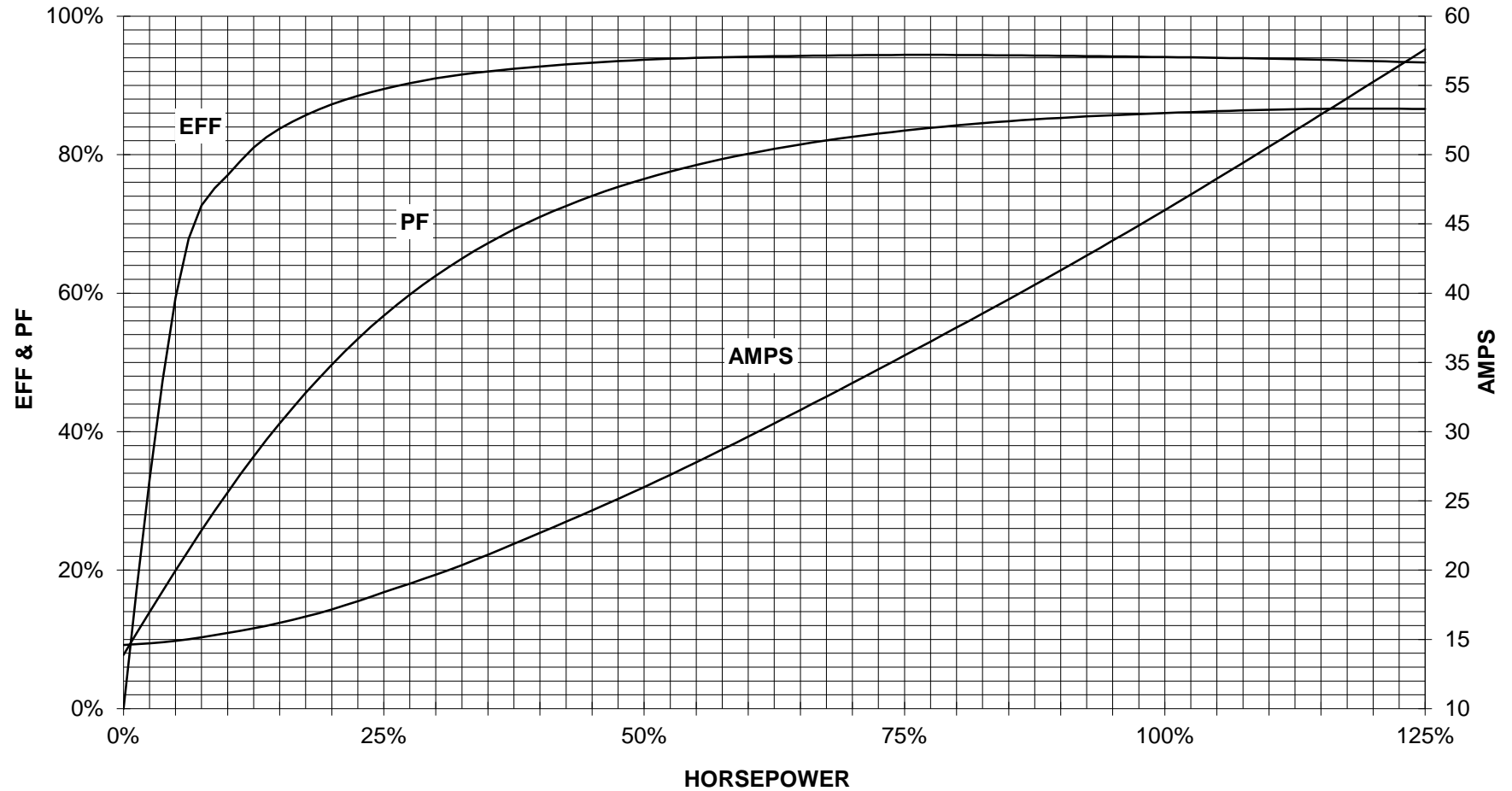
TORQUE & CURRENT VS. SPEED



CUSTOMER: _____ ORDER#: _____

40 HP 1800 RPM 324T FRAME 460 VOLTS 3 PHASE NEMA DESIGN B

SIEMENS INDUSTRY, INC.
PERFORMANCE CURVE
GP100

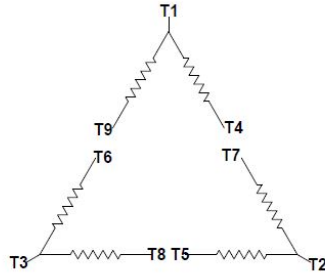


CUSTOMER: _____ ORDER #: _____

PERFORMANCE BASED ON DESIGN CALCULATIONS. SUBJECT TO CHANGE WITHOUT NOTICE.

REV. 1

Main terminal diagram



9 LEAD DELTA						
Volts	LINES			CONNECTED TOGETHER	CONN.	
	L1	L2	L3			
LOW	T1 T6	T7 T4	T8 T5	T3 T9		Δ Δ
HIGH	T1	T2	T3	T4 T7-T5 T8-T6 T9		Δ

responsible dep. DI MC LVM	technical reference	created by	approved by	Project
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