

# **(**E

# **Model Number**

#### LC20-1-DR 230VAC

Loop detector 230 V AC

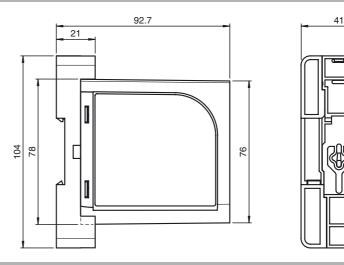
#### **Features**

- Sensor system for vehicle detection
- Complete control interface for inductive loops laid beneath the surface
- Reliable detection with long service
  life.
- Various operating modes available
- Boost function for increasing sensitivity
- Test function
- Version with 1 loop channel

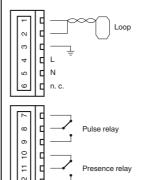
#### **Product information**

In combination with wire loops laid in the floor, loop detectors form a universal sensor system for detecting vehicles. When vehicles drive onto the loop, the resonance frequency changes. Intelligent automatic frequency selection (AFS) reduces setup time and simplifies the installation of complex multilane entrances. The evaluation process automatically and cyclically adjusts to the respective loop, so that changes in loop inductance due to temperature, humidity or component ageing are automatically compensated.

#### **Dimensions**



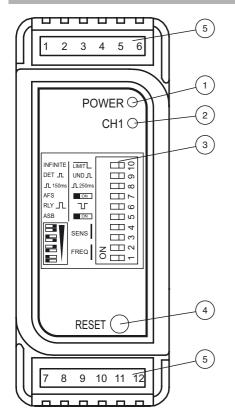
#### **Electrical connection**



#### DIN mounting rail socket

Pin assignment	Function	
1	Loop	Twist pair 1 + 2
2	Loop	TWIST PAIL T + Z
3	Earth	
4	L	Power supply
5	N	230 V ±10 % AC 50/60 Hz
6	n. c.	
7	Relay 1 NC pulse contact	
8	Relay 1 COM pulse contact	
9	Relay 1 NO pulse contact	
10	Relay 2 NC presence contact	
11	Relay 2 COM presence contact	
12	Relay 2 NO presence contact	

# Indicators/operating means

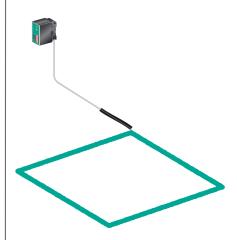


Pos. No.	Operating Elements	
1	LED power supply	
2	LED channel 1	
3	DIP switch	
4	Reset button	
5	DIN mounting rail socket	

# **Typical applications**

- Park barrier control
- Safety loop
- Arming control
- Motorized gates and doors
- Industrial control systems

# **Detection area**



**FPEPPERL+FUCHS** 

ng.xml
70100657_e
2019-11-18
Date of issue:
11-13 10:55 D
te: 2019-
elease da

Seneral specifications			
Adjustment range		Sensitivity ΔL/L 4x adjustable on the front panel 0.01 % 0.1 % with ASB overwrite option	
Function principle		Inductive loop	
Marking		CE	
Presence time		One hour for 3 % ΔL/L and option for permanent presence	
Self-tuning range		20 μΗ 1500 μΗ	
Operating frequency		4x adjustable on the front panel: 12 kHz 80 kHz (with AFS switched off)	
Operating mode		Pulsed and continuous signal	
Indicators/operating means			
Function indicator		1 x red LED: Power supply/Status , 1 x green LED: Channel status	
Control elements		DIP-switch, Refer to the documentation for functions	
Switching state		LED	
Electrical specifications			
Operating voltage	$U_B$	230 V AC ±15 %	
No-load supply current	Io	Ø 8.36 mA	
Power consumption	P <sub>0</sub>	Ø 1.92 VA	
Input			
Number of channels		1	
Output			
Output type		relay	
Signal output		Two output relays Relay 1: presence output Relay 2: pulse output	
Switching current		Relay 1 (presence output): 1 A at 230 V AC Changeover contacts (fail-safe) Relay 2 (pulse output) ≤ 1 A at 230 VAC changeover contacts (not fail-safe)	
Pulse length		150 ms or 250 ms (selected via switch)	
Response time		200 ms 300 ms	
Directive conformity			
Radio and telecommunication tern equipment	ninal	2014/53/EU	
Ambient conditions			
Operating temperature		-40 70 °C (-40 158 °F)	
Storage temperature		-40 70 °C (-40 158 °F)	
Relative humidity		max. 90 %, non-condensing	
Mechanical specifications		•	
Degree of protection		IP30	
Connection		2 x 6 plug-in screw terminals ≤1.5 mm <sup>2</sup>	
Material		· •	
Housing		ABS, anthracite	
Installation		DIN mounting rail	
installation		•	
Mass		250 g	

# **Functional Principle**

Loop detectors are control devices that are fully functional by connecting the supply voltage and an induction loop without the requirement of any additional devices. The induction wire loop laid in the floor has the inductance of a high-frequency oscillating circuit. When a vehicle drives or stands on the wire loop, the vehicle's metal parts change the frequency of the oscillating circuit. The loop detector evaluates this change and outputs it as a switching signal via volt-free relay contacts. The switching outputs are relay contacts with a high switching capacity. The spatial extent of the detection range can be varied by the size and shape of the induction loops used.

# **Programming**

#### **Presence Relay**

	Fail S	ecure	Fail Safe	
Relay	Л		T	
liolay	NO	, NC	NO	l NC
Loop not covered (No detection)	-/-			-/-
Loop covered (Detection)		-/-	-/-	
Error	-/-		-/-	
Power off	-/-		-/-	

#### **Pulse Relay**

	NO	NC
Ready	<b>→</b>	-
At an event		<b>√</b> -
Error	<b>-∕-</b>	
Power off	<b>-∕-</b>	

#### **Presence Time: DIP Switch 10**

The presence time setting determines how the detector tracks a detect. The following two selection modes are available: permanent presence and limited presence.

- Permanent presence mode: This setting maintains the presence of a vehicle over the loop by continuously compensating for all environmental
- Limited presence mode: This setting limits the presence of a vehicle over the loop with the presence time being related to the size of the detect.

Typically, a 1 %  $\Delta$  L/L will time out after approximately 1 hour.

#### Pulse on Detect or Undetect: DIP Switch 9

The pulse relay offers the following settings:

- Pulse on detect: Relay issues a pulse when detecting a vehicle drives on the loop.
- Pulse on undetect: Relay issues a pulse when detecting a vehicle that leaves the loop.

#### **Pulse Length: DIP Switch 8**

The pulse length of the pulse relay can be set to either 150 ms or 250 ms.

#### Automatic Frequency Selection (AFS): DIP Switch 7

Decide whether to use AFS or not.

- AFS on: The detector briefly evaluates all 5 frequency bands and selects the best operating frequency available. The tuning time with AFS switched on ranges between 5 s ... 20 s.
- AFS off: Select the frequency manually.

#### Fail-safe or Fail-secure: DIP Switch 6

Determine how the relay output of the presence relay is switched. Set the DIP switch to "Fail-Safe" or "Fail-Secure".

- Fail-safe setting: The output of detect is equivalent to powering off the sensor. This setting is used for access controls if persons are not to be locked out in the event of a power failure. A signal is output due to a valid detection situation or in the event of a power failure/ an error.
- Fail-secure setting: The output of non-detect is equivalent to powering off the sensor. This setting is used for access controls if persons should not be able to access the sensor in the event of a power failure. A signal is only issued due to a valid detection situation.

## Automatic Sensitivity Boost (ASB): DIP Switch 5

Use ASB to alter the undetect level of the sensor if required.

- ASB on: Boosts the sensitivity level to a maximum for detecting a vehicle, irrespective of the current sensitivity level maintained at this level during the entire presence of the vehicle over the loop. When the vehicle leaves the loop and the detection is lost, the sensitivity level reverts to the pre-selected level. ASB is used for vehicles with high beds or vehicles towing trailers to ensure detection over the entire length of the vehicle.
- ASB off: Sensitivity level remains unboosted during detection.

#### Sensitivity: DIP Switches 3 and 4

The sensitivity of the detector determines the change in inductance required for detection. The loop detector offers up to 4 sensitivity settings. Sensitivity is defined as the change in inductance. The inductance of the loop detector ranges from 0.01 % ... 0.1 %, where 0.01 % corresponds to the highest sensitivity level.

~	•	
DIP Switch 4	DIP Switch 3	Sensitivity
right	right	(0.01 %) - high sensitivity
left	right	(0.02 %) - medium high sensitivity
right	left	(0.05 %) - medium low sensitivity
left	left	(0.10 %) - low sensitivity

## Manual Frequency Selection: DIP Switches 1 and 2

Use the frequency switches to set the operating frequency of the detector. If more than one detector is used at the same location, it is necessary to set a different frequency for each detector to avoid crosstalk (interference) between adjacent loops connected to different detectors. Make sure that the loops of the detectors used are at least 2 m apart between the adjacent ends. Set each detector used at the same location to a different frequency.

DIP Switch 4	DIP Switch 3	Frequency
Right	Right	High frequency
Left	Right	Medium high frequency
Right	Left	Medium low frequency
Left	Left	Low frequency

**5 PEPPERL+FUCHS** 

#### Operation

#### Push Button for Detector Reset and for Accessing Power Failure Function

Use the multipurpose button either to reset the detector if required or to access the power failure function. The loop detector has a power failure function. In the event of a power failure, the function detects a present vehicle on the loop. This function is designed for fail-safe situations to maintain pulse output status and prevent pulse output failure in the event of a power failure.

Use the Reset push button in the following cases:

- Reset the detector.
- Switch the power failure function on/off.

The function of the reset push button depends on the duration of pushing it down (=holding time):

			3 11 ( 11 3 1,
Operating element	Purpose	Holding time	Function description
Push button	Reset	3 s	Starts the reset of the detector.
	Show power fail state	10 s	Hold for 10 seconds, to analyze the state of the power fail. If LEDs are ON, the Power Fail Toggle is ON. If LEDs are OFF, the Power Fail Toggle is OFF.
	Power Fail Toggle	30 s	After 30 seconds the Power Fail Toggle is OFF if the LEDs turn OFF. If the LEDs turn ON after 30 seconds, the Power Fail Toggle is ON.