## **Data sheet**

6ES7511-1CL03-0AB0



SIMATIC S7-1500 compact CPU CPU 1511C-1 PN, central processing unit with work memory 300 KB for program and 1.5 MB for data, 16 digital inputs, 16 digital outputs, 5 analog inputs, 2 analog outputs, 6 high-speed counters, 4 high-speed outputs for PTO/PWM/frequency output, 1st interface: PROFINET IRT with 2-port switch, 25 ns bit performance, including push-in front connector, SIMATIC Memory Card required

General information	
Product type designation	CPU 1511C-1 PN
HW functional status	FS01
Firmware version	V3.1
<ul> <li>FW update possible</li> </ul>	Yes
Product function	
• I&M data	Yes; I&M0 to I&M3
<ul> <li>Isochronous mode</li> </ul>	Yes; with minimal OB 6x cycle of 500 µs (distributed)
<ul><li>SysLog</li></ul>	Yes
Engineering with	
STEP 7 TIA Portal configurable/integrated from version	V19 (FW V3.1); with older TIA Portal versions configurable as 6ES7511-1CK00-0AB0
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	3.45 cm
Control elements	
Number of keys	8
Mode buttons	2
Supply voltage	
Rated value (DC)	24 V
permissible range, lower limit (DC)	19.2 V; 20.4 V DC, for supplying the digital inputs/outputs
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	5 ms; Refers to the power supply on the CPU section
<ul> <li>Repeat rate, min.</li> </ul>	1/s
Input current	
Current consumption (rated value)	0.62 A; without DI/DO load
Current consumption, max.	0.9 A; without DI/DO load
Inrush current, max.	1.22 A; Rated value
I²t	0.6 A <sup>2</sup> ·s
Digital inputs	
<ul> <li>from load voltage L+ (without load), max.</li> </ul>	20 mA; per group
Digital outputs	
<ul> <li>from load voltage L+, max.</li> </ul>	30 mA; Per group, without load
output voltage / header	
Rated value (DC)	24 V
Encoder supply	
Number of outputs	1; One common 24 V encoder supply

24 V angeder gunnly	
24 V encoder supply	
• 24 V	Yes; L+ (-0.8 V)
Short-circuit protection	Yes
Output current, max.	1 A
Power	
Infeed power to the backplane bus	10 W
Power consumption from the backplane bus (balanced)	8.5 W
Power loss	
Power loss, typ.	5 W
Memory	
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	
integrated (for program)	300 kbyte
• integrated (for data)	1.5 Mbyte
Load memory	
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	25 ns
for word operations, typ.	32 ns
for fixed point arithmetic, typ.	42 ns
for floating point arithmetic, typ.	170 ns
CPU-blocks	
Number of elements (total)	4 000; Blocks (OB, FB, FC, DB) and UDTs
DB	, (. , , , , , ,
Number range	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	1.5 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB	1.5 Mbyte, 1 of bbs with absolute addressing, the max. Size is 64 Nb
Number range	0 65 535
• Size, max.	300 kbyte
FC	300 kbyte
Number range	0 65 535
• Size, max.	300 kbyte
OB	Soo kbyte
	300 kbyte
• 21/6 M3X	ood nayto
Size, max.      Number of free cycle OBs	100
Number of free cycle OBs	100
<ul><li>Number of free cycle OBs</li><li>Number of time alarm OBs</li></ul>	20
<ul><li>Number of free cycle OBs</li><li>Number of time alarm OBs</li><li>Number of delay alarm OBs</li></ul>	20 20
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> </ul>	20 20 20; With minimum OB 3x cycle of 250 μs
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> </ul>	20 20 20; With minimum OB 3x cycle of 250 μs 50
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> </ul>	20 20; With minimum OB 3x cycle of 250 µs 50 3 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> </ul>	20 20; With minimum OB 3x cycle of 250 µs 50 3 1 2 100
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3 1 2 100
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of synchronous error OBs</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3 1 2 100 4
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of synchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3 1 2 100
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of aynchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> </ul> Nesting depth	20 20; With minimum OB 3x cycle of 250 µs 50 3 1 2 100 4 2 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of synchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> </ul> Nesting depth <ul> <li>per priority class</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3 1 2 100 4
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of synchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> <li>Counters, timers and their retentivity</li> </ul>	20 20; With minimum OB 3x cycle of 250 µs 50 3 1 2 100 4 2 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of aynchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> </ul> Counters, timers and their retentivity S7 counter	20 20; With minimum OB 3x cycle of 250 μs 50 3 1 2 100 4 2 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> <li>Counters, timers and their retentivity</li> <li>S7 counter</li> <li>Number</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3 1 2 100 4 2 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> <li>Counters, timers and their retentivity</li> <li>S7 counter</li> <li>Number</li> <li>Retentivity</li> </ul>	20 20; With minimum OB 3x cycle of 250 µs 50 3 1 2 100 4 2 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of synchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> <li>Counters, timers and their retentivity</li> <li>S7 counter</li> <li>Number</li> <li>Retentivity</li> <li>adjustable</li> </ul>	20 20; With minimum OB 3x cycle of 250 μs 50 3 1 2 100 4 2 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of synchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> <li>Counters, timers and their retentivity</li> <li>S7 counter</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>IEC counter</li> </ul>	20 20; With minimum OB 3x cycle of 250 µs 50 3 1 2 100 4 2 1 24  2 048
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> <li>Counters, timers and their retentivity</li> <li>S7 counter</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>IEC counter</li> <li>Number</li> </ul>	20 20; With minimum OB 3x cycle of 250 µs 50 3 1 2 100 4 2 1
<ul> <li>Number of free cycle OBs</li> <li>Number of time alarm OBs</li> <li>Number of delay alarm OBs</li> <li>Number of cyclic interrupt OBs</li> <li>Number of process alarm OBs</li> <li>Number of DPV1 alarm OBs</li> <li>Number of isochronous mode OBs</li> <li>Number of technology synchronous alarm OBs</li> <li>Number of startup OBs</li> <li>Number of asynchronous error OBs</li> <li>Number of synchronous error OBs</li> <li>Number of diagnostic alarm OBs</li> <li>Nesting depth</li> <li>per priority class</li> <li>Counters, timers and their retentivity</li> <li>S7 counter</li> <li>Number</li> <li>Retentivity</li> <li>— adjustable</li> <li>IEC counter</li> </ul>	20 20; With minimum OB 3x cycle of 250 µs 50 3 1 2 100 4 2 1 24  2 048

07 5	
S7 times	2.040
Number     Retentivity	2 048
· · · · · · · · · · · · · · · · · · ·	Yes
— adjustable  IEC timer	165
Number	Any (only limited by the main memory)
Retentivity	Any (only limited by the main memory)
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	256 kbyte; in total; available retentive memory for bit memories, timers,
	counters, DBs, and technology data (axes): 216 KB
Extended retentive data area (incl. timers, counters, flags), max.	1.5 Mbyte; When using PS 6 0W 24/48/60 V DC HF
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
Retentivity adjustable	Yes
Retentivity preset	No
Local data	CALIFORNIA ACTION ACTIO
• per priority class, max.	64 kbyte; max. 16 KB per block
Address area	0.040
Number of IO modules	2 048; max. number of modules / submodules
I/O address area	20 lebytes All insules are in the
• Inputs	32 kbyte; All cutouts are in the process image
Outputs  Per integrated IO subsystem	32 kbyte; All outputs are in the process image
per integrated IO subsystem	Oliberto
— Inputs (volume)	8 kbyte
Outputs (volume)  per CM/CP	8 kbyte
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	o ruyic
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	32; A distributed I/O system is characterized not only by the integration of
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
integrated	1
• Via CM	4; A maximum of 4 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	moorted in total
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available
	slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	10 s; Typ.: 2 s
Operating hours counter	
Number	16
Clock synchronization	
supported	Yes
supported     in AS, master	Yes Yes
• supported	

Digital inputs	
integrated channels (DI)	16
Digital inputs, parameterizable	Yes
Source/sink input	P-reading
Input characteristic curve in accordance with IEC 61131, type 3	Yes
Digital input functions, parameterizable	
Gate start/stop	Yes
Capture	Yes
Synchronization	Yes
Input voltage	
Type of input voltage	DC
Rated value (DC)	24 V
• for signal "0"	-3 to +5V
• for signal "1"	+11 to +30V
Input current	
• for signal "1", typ.	2.5 mA
Input delay (for rated value of input voltage)	
for standard inputs	
— parameterizable	Yes; none / 0.05 / 0.1 / 0.4 / 1.6 / 3.2 / 12.8 / 20 ms
— at "0" to "1", min.	4 μs; for parameterization "none"
— at "0" to "1", max.	20 ms
— at "1" to "0", min.	4 μs; for parameterization "none"
— at "1" to "0", max.	20 ms
for interrupt inputs	
— parameterizable	Yes; Same as for standard inputs
for technological functions	
— parameterizable	Yes; Same as for standard inputs
Cable length	.,,
shielded, max.	1 000 m; 600 m for technological functions; depending on input frequency,
	encoder and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; for technological functions: No
Digital outputs	
Digital outputs  Type of digital output	Transistor
	Transistor 16
Type of digital output	
Type of digital output integrated channels (DO)	16
Type of digital output integrated channels (DO) Current-sourcing Short-circuit protection  • Response threshold, typ.	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details
Type of digital output integrated channels (DO) Current-sourcing Short-circuit protection	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V
Type of digital output integrated channels (DO) Current-sourcing Short-circuit protection • Response threshold, typ. Limitation of inductive shutdown voltage to Controlling a digital input	Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes
Type of digital output integrated channels (DO) Current-sourcing Short-circuit protection • Response threshold, typ. Limitation of inductive shutdown voltage to Controlling a digital input Accuracy of pulse duration	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details
Type of digital output integrated channels (DO)  Current-sourcing Short-circuit protection  Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration minimum pulse duration	Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes
Type of digital output integrated channels (DO)  Current-sourcing Short-circuit protection  • Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration  minimum pulse duration  Digital output functions, parameterizable	Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output
Type of digital output integrated channels (DO)  Current-sourcing  Short-circuit protection  Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration  minimum pulse duration  Digital output functions, parameterizable  Switching tripped by comparison values	Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter
Type of digital output integrated channels (DO)  Current-sourcing  Short-circuit protection  Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration minimum pulse duration  Digital output functions, parameterizable  Switching tripped by comparison values  PWM output	Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes
Type of digital output integrated channels (DO) Current-sourcing Short-circuit protection • Response threshold, typ. Limitation of inductive shutdown voltage to Controlling a digital input Accuracy of pulse duration minimum pulse duration Digital output functions, parameterizable • Switching tripped by comparison values • PWM output — Number, max.	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes 4
Type of digital output integrated channels (DO)  Current-sourcing Short-circuit protection  Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration minimum pulse duration  Digital output functions, parameterizable  Switching tripped by comparison values  PWM output  Number, max.  Cycle duration, parameterizable	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes 4 Yes
Type of digital output integrated channels (DO)  Current-sourcing Short-circuit protection  Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration minimum pulse duration  Digital output functions, parameterizable  Switching tripped by comparison values  PWM output  Number, max.  Cycle duration, parameterizable  ON period, min.	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes 4 Yes 0 %
Type of digital output integrated channels (DO)  Current-sourcing  Short-circuit protection  Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration  minimum pulse duration  Digital output functions, parameterizable  Switching tripped by comparison values  PWM output  Number, max.  Cycle duration, parameterizable  ON period, min.  ON period, max.	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes 4 Yes 0 % 100 %
Type of digital output integrated channels (DO)  Current-sourcing  Short-circuit protection  Response threshold, typ.  Limitation of inductive shutdown voltage to  Controlling a digital input  Accuracy of pulse duration  minimum pulse duration  Digital output functions, parameterizable  Switching tripped by comparison values  PWM output  Number, max.  Cycle duration, parameterizable  ON period, min.  ON period, max.  Resolution of the duty cycle	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes 4 Yes 0 % 100 % 0.0036 %; For S7 analog format, min. 40 ns
Type of digital output integrated channels (DO) Current-sourcing Short-circuit protection • Response threshold, typ. Limitation of inductive shutdown voltage to Controlling a digital input Accuracy of pulse duration minimum pulse duration Digital output functions, parameterizable • Switching tripped by comparison values • PWM output — Number, max. — Cycle duration, parameterizable — ON period, min. — ON period, max. — Resolution of the duty cycle • Frequency output	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes 4 Yes 0 % 100 %
Type of digital output integrated channels (DO) Current-sourcing Short-circuit protection • Response threshold, typ. Limitation of inductive shutdown voltage to Controlling a digital input Accuracy of pulse duration minimum pulse duration Digital output functions, parameterizable • Switching tripped by comparison values • PWM output — Number, max. — Cycle duration, parameterizable — ON period, min. — ON period, max. — Resolution of the duty cycle • Frequency output Switching capacity of the outputs	16 Yes; Push-pull output Yes; electronic/thermal 1.6 A with standard output, 0.5 A with high-speed output; see manual for details connector X11: -0.8 V Yes Up to ±100 ppm ±2 μs at high-speed output; see manual for details 2 μs; With High Speed output  Yes; As output signal of a high-speed counter Yes 4 Yes 0 % 100 % 0.0036 %; For S7 analog format, min. 40 ns Yes
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	for details
• for signal "1", min.	23.2 V; L+ (-0.8 V)
Output current	23.2 V, L+ (-0.6 V)
·	0.5.A. 0.1.A with high speed output, i.e. when using a high speed output
● for signal "1" rated value	0.5 A; 0.1 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
<ul><li>for signal "1" permissible range, min.</li></ul>	2 mA
• for signal "1" permissible range, max.	0.6 A; 0.12 A with high-speed output, i.e. when using a high-speed output, observe derating; see manual for details
for signal "0" residual current, max.	0.5 mA
Output delay with resistive load	
• "0" to "1", max.	200 μs
• "1" to "0", max.	500 μs; Load-dependent
for technological functions	
— "0" to "1", max.	5 μs; Depending on the output used, see additional description in manual
— "1" to "0", max.	5 μs; Depending on the output used, see additional description in manual
Parallel switching of two outputs	
<ul> <li>for logic links</li> </ul>	Yes; for technological functions: No
<ul><li>for uprating</li></ul>	No
for redundant control of a load	Yes; for technological functions: No
Switching frequency	
<ul> <li>with resistive load, max.</li> </ul>	100 kHz; For high-speed output, 100 Hz for standard output
<ul> <li>with inductive load, max.</li> </ul>	0.5 Hz; Acc. to IEC 60947-5-1, DC-13; observe derating curve
• on lamp load, max.	10 Hz
Total current of the outputs	
Current per channel, max.	0.5 A; see additional description in the manual
Current per group, max.	8 A; see additional description in the manual
• Current per power supply, max.	4 A; 2 power supplies for each group, current per power supply max. 4 A, see additional description in manual
for technological functions	
<ul> <li>Current per channel, max.</li> </ul>	0.5 A; see additional description in the manual
Relay outputs	
<ul> <li>Number of relay outputs</li> </ul>	0
Cable length	
• shielded, max.	1 000 m; 600 m for technological functions; depending on output frequency, load, and cable quality; max. 50 m at 100 kHz
• unshielded, max.	600 m; for technological functions: No
Analog inputs	
Number of analog inputs	5; 4x for U/I, 1x for R/RTD
For current measurement	4; max.
For voltage measurement	4; max.
For resistance/resistance thermometer measurement	1
permissible input voltage for voltage input (destruction limit),	28.8 V
max.	40 mA
permissible input current for current input (destruction limit), max.	
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for details, see conversion procedure in manual
Technical unit for temperature measurement adjustable	Yes; °C/°F/K
Input ranges (rated values), voltages	Vest Dhysical recognism as a result 40.17
• 0 to +10 V	Yes; Physical measuring range: ± 10 V
— Input resistance (0 to 10 V)	100 kΩ
• 1 V to 5 V	Yes; Physical measuring range: ± 10 V
— Input resistance (1 V to 5 V)	100 kΩ
• -10 V to +10 V	Yes
<ul><li>— Input resistance (-10 V to +10 V)</li></ul>	100 kΩ
• -5 V to +5 V	Yes; Physical measuring range: ± 10 V
— Input resistance (-5 V to +5 V)	100 kΩ
Input ranges (rated values), currents	
input ranges (rateu values), currents	
• 0 to 20 mA	Yes; Physical measuring range: ± 20 mA
	Yes; Physical measuring range: $\pm$ 20 mA 50 $\Omega$ ; Plus approx. 55 ohm for overvoltage protection by PTC
• 0 to 20 mA	
0 to 20 mA     — Input resistance (0 to 20 mA)	50 $\Omega$ ; Plus approx. 55 ohm for overvoltage protection by PTC

— Input resistance (4 mA to 20 mA)	50 $\Omega$ ; Plus approx. 55 ohm for overvoltage protection by PTC
Input ranges (rated values), resistance thermometer	20 22, 1. 100 approx. 00 office of order to large protocolor by 1 10
• Ni 100	Yes; Standard/climate
— Input resistance (Ni 100)	10 ΜΩ
• Pt 100	Yes; Standard/climate
— Input resistance (Pt 100)	10 ΜΩ
Input ranges (rated values), resistors	
• 0 to 150 ohms	Yes; Physical measuring range: 0 600 ohms
— Input resistance (0 to 150 ohms)	10 ΜΩ
• 0 to 300 ohms	Yes; Physical measuring range: 0 600 ohms
<ul><li>— Input resistance (0 to 300 ohms)</li></ul>	10 ΜΩ
• 0 to 600 ohms	Yes
<ul><li>— Input resistance (0 to 600 ohms)</li></ul>	10 ΜΩ
Cable length	
<ul><li>shielded, max.</li></ul>	800 m; for U/I, 200 m for R/RTD
Analog outputs	
integrated channels (AO)	2
Voltage output, short-circuit protection	Yes
Cycle time (all channels), min.	1 ms; Dependent on the parameterized interference frequency suppression; for
Outhout roomes valles	details, see conversion procedure in manual
Output ranges, voltage	Ves
• 0 to 10 V	Yes
• 1 V to 5 V	Yes
• -10 V to +10 V	Yes
Output ranges, current  • 0 to 20 mA	Yes
• u to 20 mA • -20 mA to +20 mA	Yes
• 4 mA to 20 mA	Yes
Load impedance (in rated range of output)	100
with voltage outputs, min.	1 kΩ
with voltage outputs, min.      with voltage outputs, capacitive load, max.	100 nF
with voltage outputs, capacitive load, max.     with current outputs, max.	500 Ω
with current outputs, max.  with current outputs, inductive load, max.	1 mH
Cable length	
• shielded, max.	200 m
Analog value generation for the inputs	
Integration and conversion time/resolution per channel	
Resolution with overrange (bit including sign), max.	16 bit
Integration time, parameterizable	Yes; 2.5 / 16.67 / 20 / 100 ms, acts on all channels
Interference voltage suppression for interference frequency f1 in Hz	400 / 60 / 50 / 10
Smoothing of measured values	
parameterizable	Yes
• Step: None	Yes
Step: low	Yes
Step: Medium	Yes
Step: High	Yes
Analog value generation for the outputs	
Integration and conversion time/resolution per channel	
<ul> <li>Resolution with overrange (bit including sign), max.</li> </ul>	16 bit
Settling time	
for resistive load	1.5 ms
for capacitive load	2.5 ms
for inductive load	2.5 ms
Encoder	
Connection of signal encoders	
<ul> <li>for voltage measurement</li> </ul>	Yes
<ul> <li>for current measurement as 4-wire transducer</li> </ul>	Yes
• for resistance measurement with two-wire connection	Yes
• for resistance measurement with three-wire connection	Yes
• for resistance measurement with four-wire connection	Yes

Connectable encoders	
2-wire sensor	Yes
— permissible quiescent current (2-wire sensor), max.	1.5 mA
Encoder signals, incremental encoder (asymmetrical)	
• Input voltage	24 V
• Input frequency, max.	100 kHz
Counting frequency, max.	400 kHz; with quadruple evaluation
Signal filter, parameterizable	Yes
<ul> <li>Incremental encoder with A/B tracks, 90° phase offset</li> </ul>	Yes
Incremental encoder with A/B tracks, 90° phase offset	Yes
and zero track	
• pulse encoder	Yes
<ul> <li>pulse encoder with direction</li> </ul>	Yes
pulse encoder with one impulse signal per count direction	Yes
Errors/accuracies	
Linearity error (relative to input range), (+/-)	0.1 %
Temperature error (relative to input range), (+/-)	0.005 %/K
Crosstalk between the inputs, max.	-60 dB
Repeat accuracy in steady state at 25 °C (relative to input range), (+/-)	0.05 %
Output ripple (relative to output range, bandwidth 0 to 50 kHz), (+/-)	0.02 %
Linearity error (relative to output range), (+/-)	0.15 %
Temperature error (relative to output range), (+/-)	0.005 %/K
Crosstalk between the outputs, max.	-80 dB
Repeat accuracy in steady state at 25 °C (relative to output range), (+/-)	0.05 %
Operational error limit in overall temperature range	
<ul> <li>Voltage, relative to input range, (+/-)</li> </ul>	0.3 %
<ul> <li>Current, relative to input range, (+/-)</li> </ul>	0.3 %
<ul> <li>Resistance, relative to input range, (+/-)</li> </ul>	0.3 %
<ul> <li>Resistance thermometer, relative to input range, (+/-)</li> </ul>	Pt100 Standard: ±2 K, Pt100 Climate: ±1 K, Ni100 Standard: ±1.2 K, Ni100 Climate: ±1 K
<ul> <li>Voltage, relative to output range, (+/-)</li> </ul>	0.3 %
Current, relative to output range, (+/-)	0.3 %
Basic error limit (operational limit at 25 °C)	0.004
Voltage, relative to input range, (+/-)	0.2 %
Current, relative to input range, (+/-)      Designation relative to input range, (+/-)	0.2 %
Resistance, relative to input range, (+/-)      Resistance the research radiative to input range (+/-)	0.2 %
Resistance thermometer, relative to input range, (+/-)	Pt100 Standard: ±1 K, Pt100 Climate: ±0.5 K, Ni100 Standard: ±0.6 K, Ni100 Climate: ±0.5 K
Voltage, relative to output range, (+/-)     Current relative to output range, (+/-)	0.2 %
• Current, relative to output range, (+/-)	0.2 %
Interference voltage suppression for f = n x (f1 +/- 1 %), f1 = interference	
<ul> <li>Series mode interference (peak value of interference &lt; rated value of input range), min.</li> </ul>	30 dB
<ul> <li>Common mode voltage, max.</li> </ul>	10 V
<ul> <li>Common mode interference, min.</li> </ul>	60 dB; at 400 Hz: 50 dB
Interfaces	
Number of PROFINET interfaces	1
1. Interface	
Interface types	
• RJ 45 (Ethernet)	Yes; X1
<ul> <li>Number of ports</li> </ul>	2
integrated switch	Yes
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes

PROFINET IO Controller	
Services	
— Isochronous mode	Yes
Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
Prioritized startup	Yes; Max. 32 PROFINET devices
Number of connectable IO Devices, max.	128; In total, up to 512 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
<ul> <li>Of which IO devices with IRT, max.</li> </ul>	64
<ul> <li>Number of connectable IO Devices for RT, max.</li> </ul>	128
— of which in line, max.	128
<ul> <li>Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces
<ul> <li>Number of IO Devices per tool, max.</li> </ul>	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
— PROFINET Security Class	1
Update time for IRT	
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of $500~\mu s$ of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
<ul> <li>With IRT and parameterization of "odd" send cycles</li> </ul>	Update time = set "odd" send clock (any multiple of 125 $\mu s: 375~\mu s, 625~\mu s \dots 3~875~\mu s)$
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— Isochronous mode	No
— IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes
<ul> <li>Number of IO Controllers with shared device, max.</li> </ul>	4
<ul> <li>activation/deactivation of I-devices</li> </ul>	Yes; per user program
<ul> <li>Asset management record</li> </ul>	Yes; per user program
— PROFINET Security Class	SNMP Configuration and DCP Read Only
nterface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
<ul> <li>Autonegotiation</li> </ul>	Yes
<ul> <li>Autocrossing</li> </ul>	Yes
Industrial Ethernet status LED	Yes
Protocols	
Number of connections	
<ul> <li>Number of connections, max.</li> </ul>	128; via integrated interfaces of the CPU and connected CPs / CMs
<ul> <li>Number of connections reserved for ES/HMI/web</li> </ul>	10
<ul> <li>Number of connections via integrated interfaces</li> </ul>	88
<ul> <li>Number of S7 routing paths</li> </ul>	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
— Media redundancy	only via 1st interface (X1)
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client
MRP interconnection, supported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0

— MRPD	Yes; Requirement: IRT
<ul> <li>Switchover time on line break, typ.</li> </ul>	200 ms; For MRP, bumpless for MRPD
<ul> <li>Number of stations in the ring, max.</li> </ul>	50
SIMATIC communication	
<ul> <li>PG/OP communication</li> </ul>	Yes; encryption with TLS V1.3 pre-selected
S7 routing	Yes
<ul> <li>Data record routing</li> </ul>	Yes
<ul> <li>S7 communication, as server</li> </ul>	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
User data per job, max.	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
<ul> <li>several passive connections per port, supported</li> </ul>	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; max. 78 multicast circuits
• DHCP	Yes
• DNS	Yes
• SNMP	Yes
• DCP	Yes
• LLDP	Yes
Encryption	Yes; Optional
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
• web API	
<ul><li>— Number of sessions, max.</li></ul>	50
<ul> <li>number of simultaneous HTTP calls, max.</li> </ul>	4
— HTTP request body, max.	131 072 byte
OPC UA	
Runtime license required	Yes; "Small" license required
OPC UA Client	Yes; Data Access (registered Read/Write), Method Call
Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
Number of connections, max.	4
<ul> <li>Number of nodes of the client interfaces, recommended max.</li> </ul>	1 000
<ul> <li>Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_ReadList/OPC_I max.</li> </ul>	300
<ul> <li>Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max.</li> </ul>	20
<ul> <li>Number of elements for one call of OPC_UA_MethodGetHandleList, max.</li> </ul>	100
<ul> <li>Number of simultaneous calls of the client instructions for session management, per connection, max.</li> </ul>	1
<ul> <li>Number of simultaneous calls of the client instructions for data access, per connection, max.</li> </ul>	5
<ul> <li>Number of registerable nodes, max.</li> </ul>	5 000
<ul> <li>Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100
<ul><li>— Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li></ul>	20
OPC UA Server	Yes; Data Access (Read, Write, Subscribe), Method Call, Alarms & Condition (A&C), Custom Address Space
<ul> <li>Application authentication</li> </ul>	Yes
— Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
User authentication	"anonymous" or by user name & password

CDS cupport (cortificate management)	Yes
<ul><li>— GDS support (certificate management)</li><li>— Number of sessions, max.</li></ul>	32
Number of sessions, max.  Number of accessible variables, max.	50 000
Number of accessible variables, max.  Number of registerable nodes, max.	10 000
Number of registerable nodes, max.  Number of subscriptions per session, max.	50
— Number of subscriptions per session, max.      — Sampling interval, min.	100 ms
	200 ms
— Publishing interval, min.	200 1115
Number of server methods, max.	20
<ul> <li>Number of inputs/outputs per server method, max.</li> <li>Number of monitored items, recommended max.</li> </ul>	
,	4 000; for 1 s sampling interval and 1 s send interval
— Number of server interfaces, max.	10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace"
<ul> <li>Number of nodes for user-defined server interfaces, max.</li> </ul>	15 000
<ul> <li>Alarms and Conditions</li> </ul>	Yes
<ul> <li>Number of program alarms</li> </ul>	100
<ul> <li>Number of alarms for system diagnostics</li> </ul>	50
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	32
number of subscriptions, max.	250
number of tags/attributes for subscriptions, max.	2 000
Program alarms	Yes
Number of configurable program messages, max.	5 000; Program messages are generated by the "Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN, max.	5 000
Number of simultaneously active program alarms	
Number of program alarms	600
Number of alarms for system diagnostics	100
<ul> <li>Number of alarms for motion technology objects</li> </ul>	160
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 5 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Profiling	Yes
Status/control	
Status/control variable	Yes
<ul> <li>Variables</li> </ul>	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
Number of variables, max.	
— of which status variables, max.	200; per job
<ul> <li>of which control variables, max.</li> </ul>	200; per job
— of which control variables, max.	200; per job
Forcing	Yes
Forcing  • Forcing	Yes
Forcing	
Forcing	Yes Peripheral inputs/outputs
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer	Yes Peripheral inputs/outputs
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present	Yes Peripheral inputs/outputs 200
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present  • Number of entries, max.	Yes Peripheral inputs/outputs 200 Yes
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present	Yes Peripheral inputs/outputs 200  Yes 1 000
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present  • Number of entries, max.  — of which powerfail-proof	Yes Peripheral inputs/outputs 200  Yes 1 000
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present  • Number of entries, max.  — of which powerfail-proof  Traces	Yes Peripheral inputs/outputs 200  Yes 1 000 500
Forcing  Forcing  Forcing, variables  Number of variables, max.  Diagnostic buffer  present  Number of entries, max.  of which powerfail-proof  Traces  Number of configurable Traces	Yes Peripheral inputs/outputs 200  Yes 1 000 500
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present  • Number of entries, max.  — of which powerfail-proof  Traces  • Number of configurable Traces  Interrupts/diagnostics/status information	Yes Peripheral inputs/outputs 200  Yes 1 000 500
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present  • Number of entries, max.  — of which powerfail-proof  Traces  • Number of configurable Traces  Interrupts/diagnostics/status information  Alarms	Yes Peripheral inputs/outputs 200  Yes 1 000 500  4; Up to 512 KB of data per trace are possible
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present  • Number of entries, max.  — of which powerfail-proof  Traces  • Number of configurable Traces  Interrupts/diagnostics/status information  Alarms  • Diagnostic alarm	Yes Peripheral inputs/outputs 200  Yes 1 000 500  4; Up to 512 KB of data per trace are possible
Forcing     Forcing     Forcing, variables     Number of variables, max.  Diagnostic buffer     present     Number of entries, max.     — of which powerfail-proof  Traces     Number of configurable Traces  Interrupts/diagnostics/status information  Alarms     Diagnostic alarm     Hardware interrupt	Yes Peripheral inputs/outputs 200  Yes 1 000 500  4; Up to 512 KB of data per trace are possible
Forcing	Yes Peripheral inputs/outputs 200  Yes 1 000 500  4; Up to 512 KB of data per trace are possible  Yes Yes
Forcing  • Forcing  • Forcing, variables  • Number of variables, max.  Diagnostic buffer  • present  • Number of entries, max.  — of which powerfail-proof  Traces  • Number of configurable Traces  Interrupts/diagnostics/status information  Alarms  • Diagnostic alarm  • Hardware interrupt  Diagnoses  • Monitoring the supply voltage	Yes Peripheral inputs/outputs 200  Yes 1 000 500  4; Up to 512 KB of data per trace are possible  Yes Yes Yes

A/B transition error at incremental encoder	Yes
Diagnostics indication LED	160
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
STOP ACTIVE LED	Yes
	Yes
<ul><li>Monitoring of the supply voltage (PWR-LED)</li><li>Channel status display</li></ul>	Yes
<ul><li>for channel diagnostics</li><li>Connection display LINK TX/RX</li></ul>	Yes; For analog inputs/outputs Yes
Supported technology objects	165
Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC
Motion Control	program; selection guide via the TIA Selection Tool
<ul> <li>Number of available Motion Control resources for</li> </ul>	1 120
technology objects	
<ul> <li>Required Motion Control resources</li> </ul>	
<ul> <li>per speed-controlled axis</li> </ul>	40
<ul><li>per positioning axis</li></ul>	80
— per synchronous axis	160
— per external encoder	80
— per output cam	20
— per cam track	160
— per probe	40
<ul> <li>Positioning axis</li> </ul>	
Number of positioning axes at motion control cycle	11
of 4 ms (typical value)	44
<ul> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul>	14
Controller	
PID_Compact	Yes; Universal PID controller with integrated optimization
• PID_3Step	Yes; PID controller with integrated optimization for valves
PID-Temp	Yes; PID controller with integrated optimization for temperature
Counting and measuring	
High-speed counter	Yes
Integrated Functions	
Counter	
Number of counters	6; Of which max. 4x A/B/N
<ul> <li>Counting frequency, max.</li> </ul>	400 kHz; with quadruple evaluation
Counting functions	
Continuous counting	Yes
Counter response parameterizable	Yes
Hardware gate via digital input	Yes
Software gate	Yes
Event-controlled stop	Yes
Synchronization via digital input	Yes
Counting range, parameterizable	Yes
Comparator	
Number of comparators	2; per count channel; see manual for details
— Direction dependency	Yes
Can be changed from user program	Yes
Position detection	
Incremental acquisition	Yes
Suitable for S7-1500 Motion Control	Yes
Measuring functions	
Measuring time, parameterizable	Yes
Dynamic measurement period adjustment	Yes
Number of thresholds, parameterizable	2
Measuring range	
Frequency measurement, min.	0.04 Hz
Frequency measurement, max.	400 kHz; with quadruple evaluation
<ul> <li>Cycle duration measurement, min.</li> </ul>	
<ul><li>Cycle duration measurement, min.</li><li>Cycle duration measurement, max.</li></ul>	2.5 µs 25 s

Accuracy	
<ul> <li>Frequency measurement</li> </ul>	100 ppm; depending on measuring interval and signal evaluation
<ul> <li>Cycle duration measurement</li> </ul>	100 ppm; depending on measuring interval and signal evaluation
Velocity measurement	100 ppm; depending on measuring interval and signal evaluation
Potential separation	
Potential separation digital inputs	
<ul> <li>between the channels</li> </ul>	No
between the channels, in groups of	16
Potential separation digital outputs	
<ul> <li>between the channels</li> </ul>	No
between the channels, in groups of	16
Potential separation channels	
between the channels and backplane bus	Yes
Between the channels and load voltage L+	No
Ambient conditions	
Ambient temperature during operation	
<ul> <li>horizontal installation, min.</li> </ul>	-30 °C; No condensation
horizontal installation, max.	60 °C; note derating data for onboard I/O in the manual. Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
vertical installation, min.	-30 °C; No condensation
vertical installation, max.	40 °C; note derating data for onboard I/O in the manual. Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
Installation altitude above sea level, max.	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	V
User program protection/password protection	Yes
Copy protection	Yes
Block protection	Yes
Access protection	Von
protection of confidential configuration data     Description display.	Yes
<ul><li>Password for display</li><li>Protection level: Write protection</li></ul>	Yes Yes
Protection level: vvrite protection     Protection level: Read/write protection	
Protection level: Read/write protection     Protection level: Write protection for Failsafe	Yes No
Protection level: write protection for Fallsale     Protection level: Complete protection	Yes
User administration	Yes; device-wide
programming / cycle time monitoring / header	1 03, 00 1100 - WILL
lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	adjudano manimam opolo timo
Width	85 mm
Height	147 mm
	1.77 111111
	129 mm
Depth Weights	129 mm

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