

Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS Motor type : 1AV3112B INNOMOTICS GP - 112 M - IM V1 - 4p Offer no. Client order no. Item-No Order no. Consignment no. Project Remarks Safe Area Electrical data -/η 3) U Δ/Υ f Р Р ī М cosφ ³⁾ I_A/I_N M_A/M_N M_K/M_N IE-CL n [V] [Hz] [kW] [hp] [A] [1/min] [Nm] 4/4 3/4 4/4 I_I/I_N T_I/T_N T_B/T_N 2/4 3/4 2/4 **DOL duty (S1)** - 155(F) to 130(B) 400 Δ 50 4.00 7.90 1460 26.0 88.6 89.2 88.6 0.82 0.76 0.65 7.1 2.4 3.7 IE3 690 50 4.00 -/-1460 0.76 0.65 4.60 26.0 88.6 89.2 88.6 0.82 7.1 2.4 3.7 IE3 Δ 460 60 4.55 -/-7.70 1760 89.5 90.0 89.3 0.78 0.67 7.3 2.5 IE3 24.5 0.83 3.8 Δ -/-88.3 IE3 460 60 4.00 6.90 1770 21.5 89.5 90.0 0.81 0.72 0.60 8.2 2.9 4.3 IM V1 / IM 3011 UKCA IEC/EN 60034 IEC, DIN, ISO, VDE, EN FS 112 M Environmental conditions: -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold): 16.1 s | 21.8 s Mechanical data Sound level (SPL / SWL) at 50Hz|60Hz 58 / 70 dB(A) 2) 3) 62 / 74 dB(A) 2) 3) External earthing terminal Without Moment of inertia 0.0170 kg m² Vibration severity grade Α Bearing DE | NDE 6206 Z C3 6206 Z C3 Thermal class F bearing lifetime Duty type **S**1 $L_{10mh}\,F_{Rad\,\,min}$ for coupling operation $50|60Hz^{\,1)}$ 20000 h 16000 h Direction of rotation bidirectional 5 g | 5 g 8000 h Relubrication interval/quantity DE | NDE Frame material aluminum Net weight of the motor (IM B3) 34 kg Lubricants Unirex N3 Regreasing device With Coating (paint finish) Standard paint finish C2 Grease nipple M8x1 DIN 71412 Color, paint shade RAL7030 Type of bearing Preloaded bearing DE Motor protection (B) 3 PTC thermistors - for tripping (2 terminals) Condensate drainage holes Without Method of cooling IC411 - self ventilated, surface cooled Terminal box Terminal box position Max. cross-sectional area 4 mm^2 top Material of terminal box Aluminium Cable diameter from ... to ... 11 mm - 21 mm TB1 F00 Type of terminal box Cable entry 2xM32x1,5-1xM16x1,5 Contact screw thread M4 Cable gland 3 plugs 1) L_{10mh} according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411 IA/IN = locked rotor current / current nominal M_A/M_N = locked rotor torque / torque nominal 2) at rated power / at full load M_K/M_N = break down torque / nominal torque Transmittal, reproduction, dissemination and/or editing of this document as well as utilization of its contents and communication thereof to others without express authorization are prohibited. Offenders will be held liable for payment of damages. All rights created by patent grant or registration of a utility model or design patent are reserved.

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	Document type				Document s	tatus		
INNOMOTICS	Technical data sheet				Released			
	Document title				Document number			
	1LE1003-1BB23-4GB4-Z				TDS-241014-095939			
Restricted	H00+L23				Revision	Creation date	Language	Page
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