Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS Motor type: 1CV3112B INNOMOTICS SD - 112 M - IM B3 - 4p Offer no. Client order no. Item-No Order no. Consignment no. Project Remarks Safe Area Electrical data -/-Δ/Υ U f Р Р ī М η 3)  $cos\phi^{\ 3)}$  $I_A/I_N$ M<sub>A</sub>/M<sub>N</sub>  $M_K/M_N$ IE-CL n [V] [Hz] [kW] [hp] [A] [1/min] [Nm] 4/4 3/4 4/4 2/4  $I_I/I_N$  $T_I/T_N$  $T_B/T_N$ 2/4 3/4 **DOL duty (S1)** - 155(F) to 130(B) 400 Δ 50 4.00 7.90 1460 26.0 88.6 89.2 88.6 0.82 0.76 0.65 7.1 2.4 3.7 IE3 690 50 4.00 -/-1460 0.76 0.65 3.7 IE3 4.60 26.0 88.6 89.2 88.6 0.82 7.1 2.4 Δ 460 60 4.55 -/-7.70 1760 24.5 89.5 90.0 89.3 0.78 0.67 7.3 2.5 IE3 0.83 3.8 Δ -/-IE3 460 60 4.00 6.90 1770 21.5 89.5 90.0 88.3 0.81 0.72 0.60 8.2 2.9 4.3 IM B3 / IM 1001 FS 112 M UKCA IEC/EN 60034 IEC, DIN, ISO, VDE, EN Environmental conditions: -20 °C - +40 °C / 1000 m Locked rotor time (hot / cold): 16.1 s | 21.8 s Mechanical data 58 / 70 dB(A) 2) 3) Sound level (SPL / SWL) at 50Hz|60Hz 62 / 74 dB(A) 2) 3) Vibration severity grade Α 0.0170 kg m<sup>2</sup> Thermal class Moment of inertia F Bearing DE | NDE **S**1 6306 2Z C3 6306 2Z C3 Duty type bearing lifetime Direction of rotation bidirectional  $L_{10mh}\,F_{Rad\,\,min}$  for coupling operation  $50|60Hz^{\,1)}$ 40000 h 32000 h Frame material cast iron Regreasing device Without Net weight of the motor (IM B3) 46 kg Coating (paint finish) Special paint finish C3 Grease nipple Preloaded bearing DE Color, paint shade RAL7030 Type of bearing (B) 3 PTC thermistors - for tripping (standard) (2 terminals) Condensate drainage holes With (standard) Motor protection External earthing terminal Without Method of cooling IC411 - self ventilated, surface cooled Terminal box Terminal box position top Max. cross-sectional area 4 mm<sup>2</sup> Material of terminal box cast iron Cable diameter from ... to ... 11 mm - 21 mm Type of terminal box TB1 F01 2xM32x1,5-1xM16x1,5 Cable entry Contact screw thread Μ4 Cable gland 3 plugs 1) L<sub>10mh</sub> according to DIN ISO 281 10/2010 3) Value is valid only for DOL operation with motor design IC411 IA/IN = locked rotor current / current nominal M<sub>A</sub>/M<sub>N</sub> = locked rotor torque / torque nominal 2) at rated power / at full load M<sub>K</sub>/M<sub>N</sub> = break down torque / nominal torque Transmittal, reproduction, dissemination and/or editing of this document as well as utilization of its contents and communication thereof to others without express authorization are prohibited. Offenders will be held liable for payment of damages. All rights created by patent grant or registration of a utility model or design patent are reserved.

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