

Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS



Motor type : 1CV3136B

SIMOTICS SD - 132 M - IM V1 - 4p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Safe Area

Electrical data

-/-

U [V]	Δ / Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	$\eta^{3)}$			$\cos\phi^{3)}$			I_A/I_N I_f/I_N	M_A/M_N T_f/T_N	M_K/M_N T_B/T_N	IE-CL
								4/4	3/4	2/4	4/4	3/4	2/4				
DOL duty (S1) - 155(F) to 130(B)																	
230	Δ	50	11.00	-/-	38.00	1470	71.0	91.4	91.8	91.1	0.79	0.73	0.61	8.3	2.8	3.8	IE3
400	Y	50	11.00	-/-	22.00	1470	71.0	91.4	91.8	91.1	0.79	0.73	0.61	8.3	2.8	3.8	IE3
460	Y	60	12.60	-/-	21.00	1770	68.0	92.4	92.6	92.0	0.81	0.76	0.65	8.8	2.7	3.8	IE3
460	Y	60	11.00	-/-	19.20	1775	59.0	92.4	92.0	91.0	0.78	0.72	0.60	9.8	3.1	4.4	IE3
IM V1 / IM 3011		FS 132 M		IP55		UKCA		IEC/EN 60034		IEC, DIN, ISO, VDE, EN							
Environmental conditions : -20 °C - +40 °C / 1000 m										Locked rotor time (hot / cold) : 14.4 s 20.6 s							

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	64 / 78 dB(A) ^{2) 3)}	69 / 82 dB(A) ^{2) 3)}	Vibration severity grade	A
Moment of inertia	0.0410 kg m ²		Thermal class	F
Bearing DE NDE	6308 2Z C3	6308 2Z C3	Duty type	S1
bearing lifetime			Direction of rotation	bidirectional
L_{10mh} $F_{Rad, min}$ for coupling operation 50 60Hz ¹⁾	20000 h	16000 h	Frame material	cast iron
Regreasing device	Without		Net weight of the motor (IM B3)	99 kg
Grease nipple	-/-		Coating (paint finish)	Special paint finish C3
Type of bearing	Preloaded bearing DE		Color, paint shade	RAL7030
Condensate drainage holes	With (standard)		Motor protection	(B) 3 PTC thermistors - for tripping (standard) (2 terminals)
External earthing terminal	Without		Method of cooling	IC416 - separately ventilated, surface cooled

Terminal box

Terminal box position	top	Max. cross-sectional area	6 mm ²
Material of terminal box	cast iron	Cable diameter from ... to ...	11 mm - 21 mm
Type of terminal box	TB1 H01	Cable entry	2xM32x1,5-1xM16x1,5
Contact screw thread	M4	Cable gland	3 plugs

I_A/I_N = locked rotor current / current nominal
 M_A/M_N = locked rotor torque / torque nominal
 M_K/M_N = break down torque / nominal torque
 1) L_{10mh} according to DIN ISO 281 10/2010
 2) at rated power / at full load
 3) Value is valid only for DOL operation with motor design IC411

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Special design

F70	Mounting of separately driven fan	H00	Canopy
G12	Rotary pulse encoder Sendix 5020 (TTL)	M01	Connection when shipped, star connection

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