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Data sheet for SINAMICS G120X

Article No. :

6SL3230-1YE38-0AF0



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks :

Rated data		
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10	% -20 %
Line frequency	47 63 Hz	
Rated voltage	400V IEC	480V NEC
Rated current (LO)	86.00 A	74.00 A
Rated current (HO)	78.00 A	69.00 A
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC ¹⁾
Rated power (LO)	45.00 kW	60.00 hp
Rated power (HO)	37.00 kW	50.00 hp
Rated current (LO)	90.00 A	77.00 A
Rated current (HO)	75.00 A	65.00 A
Rated current (IN)	93.00 A	
Max. output current	122.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications			
Power factor λ	0.90 0.95		
Offset factor $\cos \phi$	0.99		
Efficiency η	0.97		
Sound pressure level (1m)	70 dB		
Power loss ³⁾	1.340 kW		
Filter class (integrated)	RFI suppression filter for Category C2		
EMC category (with accessories)	Category C2		
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)		
Communication			

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

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Inputs / outputs			
Standard digital inputs			
Number	6		
Switching level: $0 \rightarrow 1$	11 V		
Switching level: $1 \rightarrow 0$	5 V		
Max. inrush current	15 mA		
Fail-safe digital inputs			
Number	1		
Digital outputs			
Number as relay changeover contact	2		
Output (resistive load)	DC 30 V, 5.0 A		
Number as transistor	0		
Analog / digital inputs			
Number	2 (Differential input)		
Resolution	10 bit		
Switching threshold as digital input			
$0 \rightarrow 1$	4 V		
$1 \rightarrow 0$	1.6 V		
Analog outputs			
Number	1 (Non-isolated output)		
PTC/ KTY interface			
1 motor temperature sensor input, sensors that can be connected PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$			
Closed-loop control techniques			

closed-loop control techniques		
V/f linear / square-law / parameterizable	Yes	
V/f with flux current control (FCC)	Yes	
V/f ECO linear / square-law	Yes	
Sensorless vector control	Yes	
Vector control, with sensor	No	
Encoderless torque control	No	
Torque control, with encoder	No	

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Ambient conditions			
Standard board coating type	Class 3C3, according to IEC 60721-3-3: 2002		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.083 m³/s (2.931 ft³/s)		
Installation altitude	1,000 m (3,280.84 ft)		
Ambient temperature			
Operation	-20 45 °C (-4 113 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-25 55 °C (-13 131 °F)		
Relative humidity			
Max. operation	95 % At 40 °C (104 °F), condensation and icing not permissible		
Connections			
Signal cable			
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)		
Line side			
Version	screw-type terminal		
Conductor cross-section	25.00 70.00 mm² (AWG 6 AWG 3/0)		
Motor end			
Version	Screw-type terminals		
Conductor cross-section	25.00 70.00 mm² (AWG 6 AWG 3/0)		
DC link (for braking resistor)			
PE connection	Screw-type terminals		
Max. motor cable length			
Max. motor cable length Shielded	150 m (492.13 ft)		

Ме	chanical data	
Degree of protection	IP20 / UL open	type
Frame size	FSE	
Net weight	29 kg (63.93 lb)	
Dimensions		
Width	275 mm (10.8	3 in)
Height	551 mm (21.69 in)	
Depth	248 mm (9.76	in)
	Standards	
Compliance with standards	UL, cUL, CE, C- SEMI F47, REA	Tick (RCM), EAC, KCC, CH
CE marking	EMC Directive Voltage Directi	2004/108/EC, Low- ve 2006/95/EC
Converter lo	osses to IEC61800-	9-2*
Efficiency class	IE2	
Comparison with the reference converter (90% / 100%)	45.5 %	
■ 951.0 W (1.5 %)	1,100.0 W (1.8 %)	1,340.0 W (2.2 %)
543.0 W (0.9 %)	598.0 W (1.0 %)	678.0 W (1.1 %)
403.0 W (0.7 %)	427.0 W (0.7 %)	
	50%	90% f

The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*calculated values

¹⁾The output current and HP ratings are valid for the voltage range 440V-480V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.