## Product data sheet <br> Characteristics <br> ATV61EXC2C31N4 <br> enclosed variable speed drive ATV61 Plus 310 kW - 400V - IP23



| Range of product | Altivar 61 Plus |
| :---: | :---: |
| Product or component type | Variable speed drive |
| Device short name | ATV61 |
| Product destination | Asynchronous motors Synchronous motors |
| Product specific application | Pumping and ventilation machine |
| Assembly style | In floor-standing enclosure compact version |
| Product composition | A line choke <br> A switch and fast-acting fuses <br> An IP65 remote mounting kit for graphic display terminal <br> A wired ready-assembled Sarel Spacial 6000 enclosure <br> Terminals/Bars for motor connection <br> ATV61HC31N4D standard drive IP00 |
| EMC filter | Integrated |
| Network number of phases | 3 phases |
| Rated supply voltage | 380... 415 V (+/-10 \%) |
| Supply voltage limits | 342... 457 V |
| Supply frequency | $50 . . .60 \mathrm{~Hz}(-5 . . .5$ \%) |
| Network frequency limits | 47.5... 63 Hz |
| Motor power kW | 315 kW, 3 phases at 380... 415 V |
| Line current | 527 A for 400 V 3 phases / 315 kW |
| IP degree of protection | IP23 |


| Complementary |  |
| :---: | :---: |
| Apparent power | 365 kVA for 400 V , 3 phases 315 kW |
| Prospective line Isc | 100 kA with external fuses |
| Continuous output current | 616 A at $2.5 \mathrm{kHz}, 400 \mathrm{~V} 3$ phases |
| Maximum transient current | 739 A for $60 \mathrm{~s}, 3$ phases |
| Speed drive output frequency | 0.1.. 500 Hz |
| Nominal switching frequency | 2.5 kHz |
| Switching frequency | $2.5 . .8 \mathrm{kHz}$ with derating factor $2 . . .8 \mathrm{kHz}$ adjustable |
| Speed range | 1... 100 in open-loop mode, without speed feedback |
| Speed accuracy | +/-10 \% of nominal slip for 0.2 Tn to Tn torque variation without speed feedback |
| Torque accuracy | +/- $15 \%$ in open-loop mode, without speed feedback |
| Transient overtorque | 135 \% of nominal motor torque for 2 s 120 \% of nominal motor torque for 60 s |
| Braking torque | 30 \% without braking resistor <= 125 \% with braking resistor |
| Asynchronous motor control profile | Energy saving ratio <br> Voltage/Frequency ratio (2 or 5 points) <br> Flux vector control without sensor, standard |
| Synchronous motor control profile | Vector control without sensor, standard |
| Regulation loop | Adjustable PI regulator |


| Motor slip compensation | Adjustable <br> Automatic whatever the load <br> Can be suppressed <br> Not available in voltage/frequency ratio (2 or 5 points) |
| :---: | :---: |
| Overvoltage category | Class 3 conforming to EN 50178 |
| Local signalling | LCD display unit - operation function, status and configuration - mounted in the front door |
| Output voltage | <= power supply voltage |
| Isolation | Between power and control terminals |
| Type of cable for external connection | IEC cable at $40{ }^{\circ} \mathrm{C}$, copper $70{ }^{\circ} \mathrm{C} / \mathrm{PVC}$ |
| Electrical connection | Terminal M12-3x $185 \mathrm{~mm}^{2}$ (L1/R, L2/S, L3/T) entry from the bottom Terminal M12-4×240 mm² (U/T1, V/T2, W/T3) entry from the bottom Terminal - $2.5 \mathrm{~mm}^{2}$ / AWG 14 (Al1-/Al1+, Al2, AO1, R1A, R1B, R1C, R2A, R2B, LI1...LI6, PWR) entry from the bottom |
| Motor recommanded cable cross section | $3(3 \times 150) \mathrm{mm}^{2}$ |
| Short circuit protection | 800 A fuse protection (gl fuse) on power supply upstream |
| Supply | Internal supply : 24 V DC ( $21 \ldots 27 \mathrm{~V}$ ), $0 . . .100 \mathrm{~mA}$ Internal supply for reference potentiometer : 10 V DC ( $10 . . .11 \mathrm{~V}$ ), $0 . . .10 \mathrm{~mA}$ External supply : 24 V DC (19... 30 V ), $1 \mathrm{~A}, 30 \mathrm{~W}$ |
| Analogue input number | 2 |
| Analogue input type | Software-configurable current : (AI2) $0 \ldots 20 \mathrm{~mA} / 4 \ldots 20 \mathrm{~mA}-250$ Ohm - sampling time: $1.5 . . .2 .5 \mathrm{~ms}$ - resolution: 11 bits Bipolar differential voltage : (Al1-/Al1+) +/-10 V DC - 24 V max - sampling time: $1.5 . . .2 .5 \mathrm{~ms}$ - resolution: 11 bits + sign <br> Software-configurable voltage : (AI2) $0 . . .10 \mathrm{~V}$ DC - 24 V max - 30 kOhm - sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$ - resolution: 11 bits |
| Analogue output number | 1 |
| Analogue output type | Software-configurable current : (AO1) $0 . . .20 \mathrm{~mA} / 4 \ldots 20 \mathrm{~mA}-500$ Ohm - sampling time: $1.5 \ldots . .2 .5 \mathrm{~ms}$ - resolution: 10 bits <br> Software-configurable voltage : (AO1) $0 . . .10 \mathrm{~V}$ DC - 470 Ohm - sampling time: $1.5 \ldots 2.5 \mathrm{~ms}$ - resolution: 10 bits |
| Discrete output number | 2 |
| Discrete output type | Configurable relay logic : (R2A, R2B) NO - 6.5 ... $7.5 \mathrm{~ms}-100000$ cycles Configurable relay logic : (R1A, R1B, R1C) NO/NC - 6.5 ... $7.5 \mathrm{~ms}-100000$ cycles |
| Minimum switching current | 3 mA at 24 V DC (configurable relay logic) |
| Maximum switching current | 2 A at $30 \mathrm{~V} D C$ on inductive load $-\mathrm{L} / \mathrm{R}=7 \mathrm{~ms}$ (configurable relay logic) 2 A at 250 V AC on inductive load $-\cos \mathrm{phi}=0.4$ (configurable relay logic) 5 A at 30 V DC on resistive load $-\mathrm{L} / \mathrm{R}=0 \mathrm{~ms}$ (configurable relay logic) 5 A at 250 V AC on resistive load $-\cos$ phi = 1 (configurable relay logic) |
| Discrete input number | 7 |
| Discrete input type | Safety input (PWR) 24 V DC (<= 30 V ) -1.5 kOhm <br> Switch-configurable (LI6) 24 V DC (<= 30 V ), with level 1 PLC - 1.5 kOhm - sampling time: 1.5 ... 2.5 ms <br> Programmable (LI1...LI5) 24 V DC (<= 30 V ), with level 1 PLC - 3.5 kOhm - sampling time: $1.5 . . .2 .5 \mathrm{~ms}$ |
| Discrete input logic | $\begin{aligned} & \text { Positive logic (source) (PWR), } 0 \ldots 2 \mathrm{~V} \text { (state 0), } 17 \ldots 30 \mathrm{~V} \text { (state } 1) \\ & \text { Negative logic (sink) (LII ...LI6), } 16 \ldots 30 \mathrm{~V} \text { (state 0), } 0 \ldots 10 \mathrm{~V} \text { (state 1) } \\ & \text { Positive logic (source) (LI1...LI6), } 0 \ldots 5 \mathrm{~V} \text { (state 0), } 11 \ldots . .30 \mathrm{~V} \text { (state 1) } \end{aligned}$ |
| Acceleration and deceleration ramps | Linear adjustable separately from 0.01 to 9000 s S, U or customized |
| Braking to standstill | By DC injection |
| Protection type | Thermal protection for motor <br> Power removal for motor <br> Motor phase break for motor <br> Thermal protection for drive <br> Short-circuit between motor phases for drive <br> Power removal for drive <br> Overvoltages on the DC bus for drive <br> Overheating protection for drive <br> Overcurrent between output phases and earth for drive <br> Line supply undervoltage for drive <br> Line supply overvoltage for drive <br> Input phase breaks for drive <br> Break on the control circuit for drive <br> Against input phase loss for drive <br> Against exceeding limit speed for drive |
| Dielectric strength | 5092 V DC between control and power terminals 3535 V DC between earth and power terminals |
| Insulation resistance | > 1 mOhm at 500 V DC for 1 minute to earth |


| Frequency resolution | 0.1 Hz for display unit $0.024 / 50 \mathrm{~Hz}$ for analog input |
| :---: | :---: |
| Communication port protocol | CANopen Modbus |
| Type of connector | Male SUB-D 9 on RJ45 for CANopen <br> 1 RJ45 for Modbus on terminal <br> 1 RJ45 for Modbus on front face |
| Physical interface | 2-wire RS 485 for Modbus |
| Transmission frame | RTU for Modbus |
| Transmission rate | $20 \mathrm{kbps}, 50 \mathrm{kbps}, 125 \mathrm{kbps}, 250 \mathrm{kbps}, 500 \mathrm{kbps}, 1 \mathrm{Mbps}$ for CANopen 9600 bps, 19200 bps for Modbus on front face <br> $4800 \mathrm{bps}, 9600 \mathrm{bps}, 19200 \mathrm{bps}, 38.4 \mathrm{Kbps}$ for Modbus on terminal |
| Data format | 8 bits, odd even or no configurable parity for Modbus on terminal 8 bits, 1 stop, even parity for Modbus on front face |
| Type of polarization | No impedance for Modbus |
| Number of addresses | 1... 247 for Modbus <br> 1... 127 for CANopen |
| Method of access | Slave for CANopen |
| Function available | Isolated amplifier for control circuit <br> Adaptor for 115 V logic inputs for control circuit <br> Control terminals for control circuit <br> External 24 V DC supply terminals for power circuit <br> Relay output C/O for control circuit <br> Braking unit for power circuit <br> Enclosure plinth for power circuit <br> Cable entry via the top for power circuit <br> Motor choke for power circuit <br> Enclosure heating for power circuit <br> Ammeter for power circuit <br> 12-pulse supply for power circuit <br> Line contactor for power circuit <br> Door handle for main switch for power circuit <br> Voltmeter for power circuit <br> External motor fan for power circuit <br> Motor heating for power circuit <br> Key switch (local/remote) for power circuit <br> Enclosure lighting for power circuit <br> Buffer voltage 24 V DC power supply for power circuit <br> External 230 V supply terminals for power circuit <br> Design for IT networks for power circuit <br> Insulation monitoring for power circuit <br> Pt100 relay for power circuit <br> PTC relay for power circuit <br> Safe standstill for power circuit |
| Option card | Encoder interface cards <br> Extended I/O extension card <br> Basic I/O extension card <br> Multi-pump card <br> Controller inside programmable card <br> Communication card for Profibus DP V1 <br> Communication card for Profibus DP <br> Communication card for Modbus/Uni-Telway <br> Communication card for Modbus TCP <br> Communication card for Modbus Plus <br> Communication card for METASYS N2 <br> Communication card for LonWorks <br> Communication card for Interbus-S <br> Communication card for Fipio <br> Communication card for Ethernet/IP <br> Communication card for DeviceNet <br> Communication card for CC-Link <br> Communication card for BACnet <br> Communication card for APOGEE FLN |
| Operating position | Vertical +/- 10 degree |
| Colour of enclosure | Light grey RAL 7035 |
| Width | 800 mm |
| Height | 2162 mm |
| Depth | 642 mm |
| Product weight | 485 kg |


| Environment |  |
| :--- | :--- |
| Electromagnetic compatibility | Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 |
|  | Radiated radio-frequency electromagnetic field immunity test level 3 conforming |
|  | to IEC 61000-4-3 |
|  | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 |
|  | Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 |
|  | Conducted radio-frequency immunity test level 3 conforming to IEC $61000-4-6$ |
| $1.2 / 50 ~ \mu \mathrm{~s}-8 / 20 \mu \mathrm{~s}$ surge immunity test level 3 conforming to IEC 61000-4-5 |  |

## Product data sheet

## ATV61EXC2C31N4

## Dimensions Drawings

## IP 23 Floor-Standing Enclosure Compact Version

Standard Compact Floor-Standing Enclosure


Standard Compact Floor-Standing Enclosure + Additional Floor-Standing Enclosures, According to the Configuration

(1) Seal. For each floor-standing enclosure added, allow a $4 \mathrm{~mm} / 0.15 \mathrm{in}$. space for the seal.
(2) Standard IP 23 compact version floor-standing enclosure.

NOTE: The position of the enclosures must be complied with during installation. The number of additional enclosures can vary according to the chosen configuration.

| Options | a | a1 | a2 | a3 | a4 |
| :--- | :--- | :--- | :--- | :--- | :--- |
| With or without common options or options (6) <br> dependent on the drive rating | $816 \mathrm{~mm} / 32.1 \mathrm{in}$. | - | - | - | $816 \mathrm{~mm} / 32.1 \mathrm{in}$. |
| Cable entry via the top option (4) | $808 \mathrm{~mm} / 31.8 \mathrm{in}$. | - | $408 \mathrm{~mm} / 16 \mathrm{in}$. | - | $1220 \mathrm{~mm} / 48 \mathrm{in}$. |
| Sinus filter option | $808 \mathrm{~mm} / 31.8 \mathrm{in}$. | - | - | $608 \mathrm{~mm} / 23.9 \mathrm{in}$. | $1420 \mathrm{~mm} / 55.9 \mathrm{in}$. |
| (3) Except sinus filter option, which requires an additional enclosure. The sinus filter option is not compatible with the cable entry via the |  |  |  |  |  |
| (4) The cable entry via the top option is not compatible with the sinus filter option. |  |  |  |  |  |

Wiring Diagram


A1 Drive
A2 Enclosure
F1 Fast-acting semi-conductor fuse
IL1 Line choke
Q1 Switch
(1) Fault relay contacts. For remote signalling of drive status.

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## Derating Curves

The derating curves for the drive nominal current (In) are dependent on the temperature and switching frequency. For intermediate temperatures, interpolate between 2 curves.
NOTE: The drive will reduce the switching frequency automatically in the event of excessive temperature rise.
$1 / n(\%)$


X Switching frequency ( kHz )
NOTE: The temperatures shown correspond to the temperature of the air entering the enclosure.

